

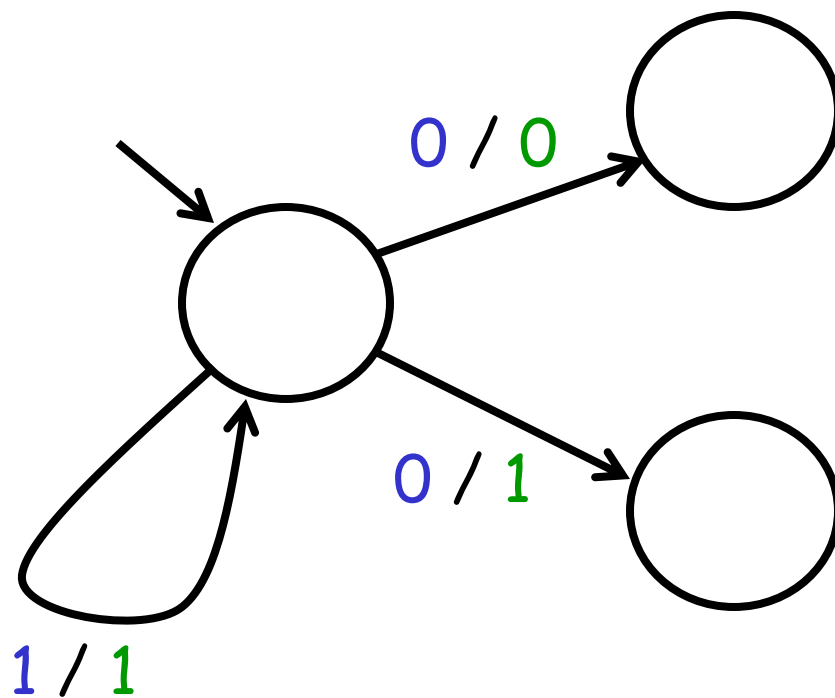
Nondeterminism

EECS 20

Lecture 14 (February 16, 2001)

Tom Henzinger

Nondeterminism



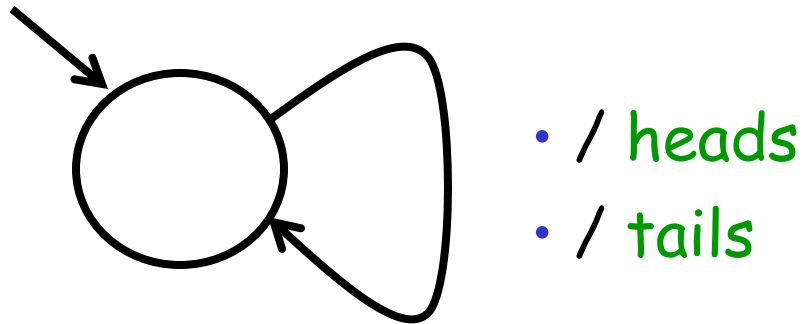
Nondeterminism

- modeling randomness
- modeling abstraction
- modeling uncertainty
- modeling properties

Modeling Randomness: Coin Tossing



Modeling Randomness: Coin Tossing



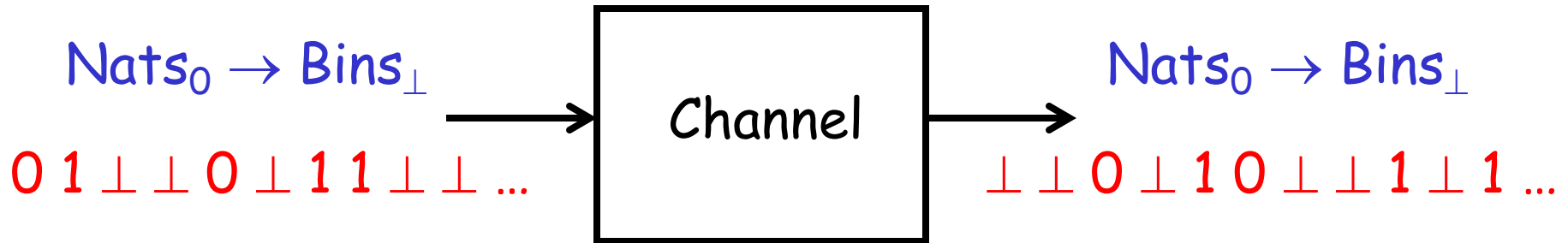
One possible behavior

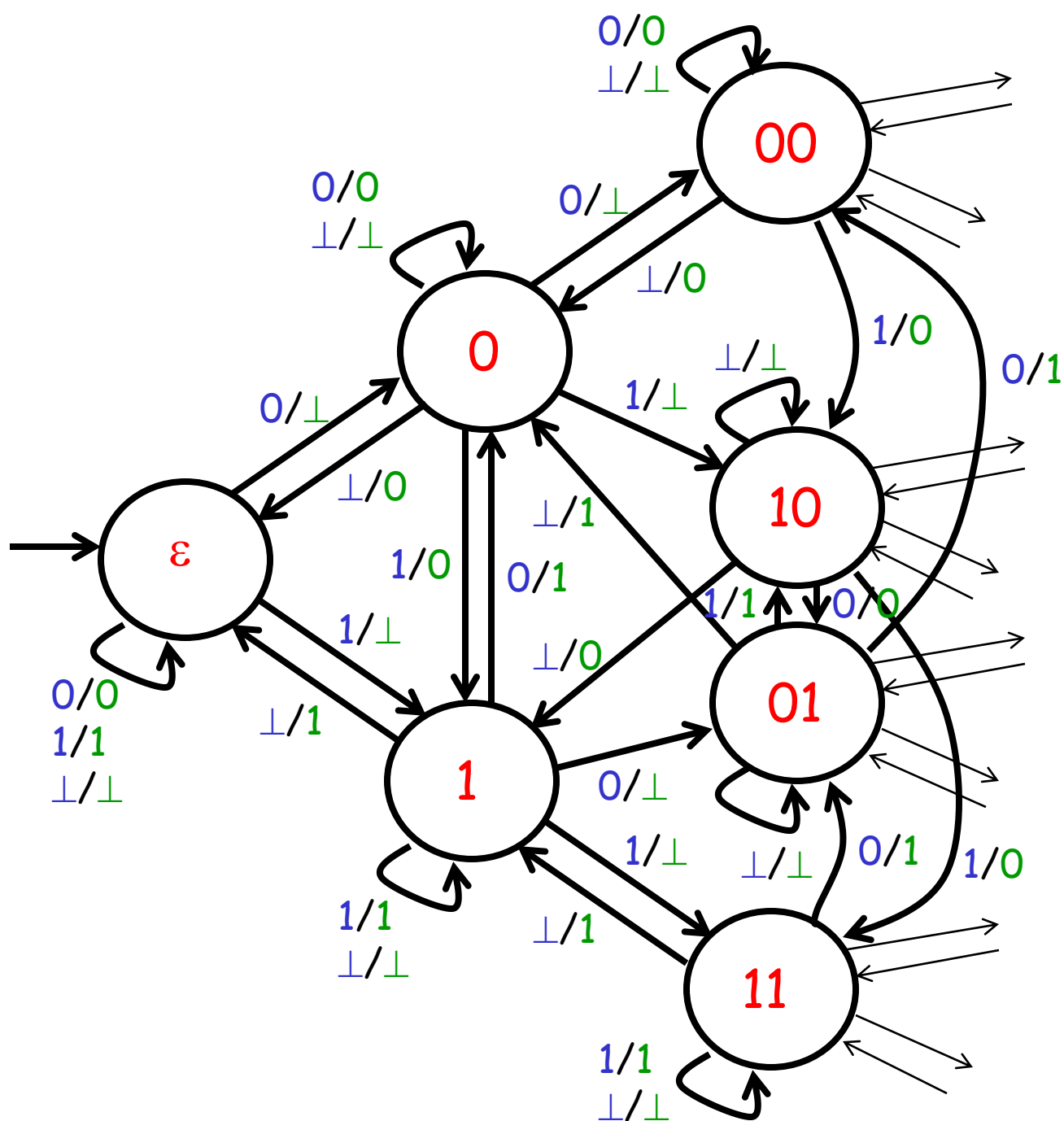
Time	0	1	2	3	4
Input	•	•	•	•	•
Output	heads	heads	tails	heads	tails

Another possible behavior

Time	0	1	2	3	4
Input	•	•	•	•	•
Output	tails	heads	tails	heads	heads

Modeling Abstraction: Channel Latency





State =
channel
contents

One possible run

Time	0	1	2	3	4	5	
Input	0	1	⊥	0	⊥	⊥	
Output	⊥	⊥	⊥	0	⊥	1	
State	ε	0	10	10	01	01	0

One possible run

Time	0	1	2	3	4	5	
Input	0	1	⊥	0	⊥	⊥	
Output	⊥	⊥	⊥	0	⊥	1	
State	ε	0	10	10	01	01	0

Corresponding behavior

Time	0	1	2	3	4	5
Input	0	1	\perp	0	\perp	\perp
Output	\perp	\perp	\perp	0	\perp	1

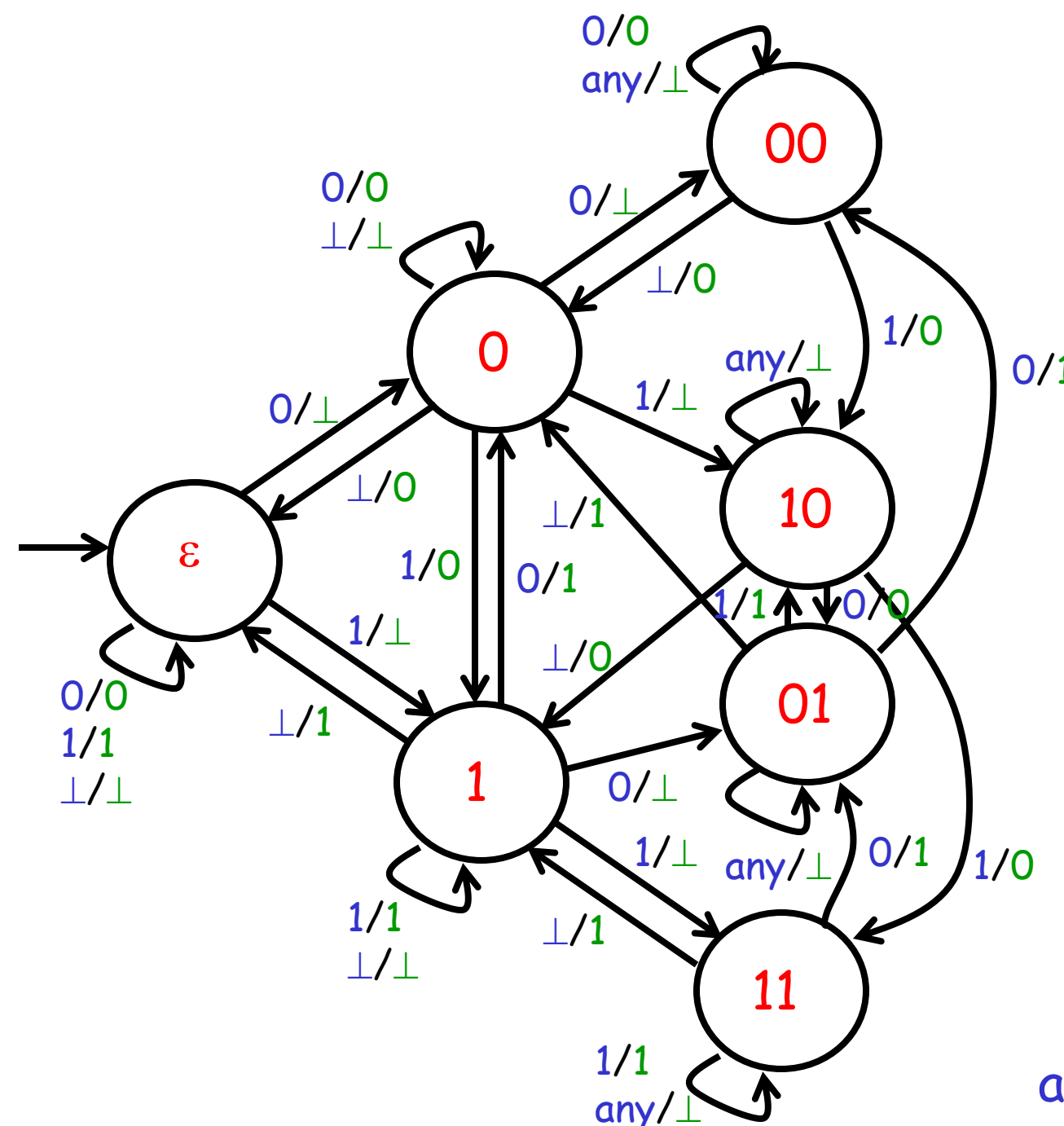
One possible run

Time	0	1	2	3	4	5	
Input	0	1	⊥	0	⊥	⊥	
Output	⊥	⊥	⊥	0	⊥	1	
State	ε	0	10	10	01	01	0

Another possible run on the same input signal

Input	0	1	⊥	0	⊥	⊥	
Output	⊥	⊥	0	1	⊥	0	
State	ε	0	10	1	0	0	ε

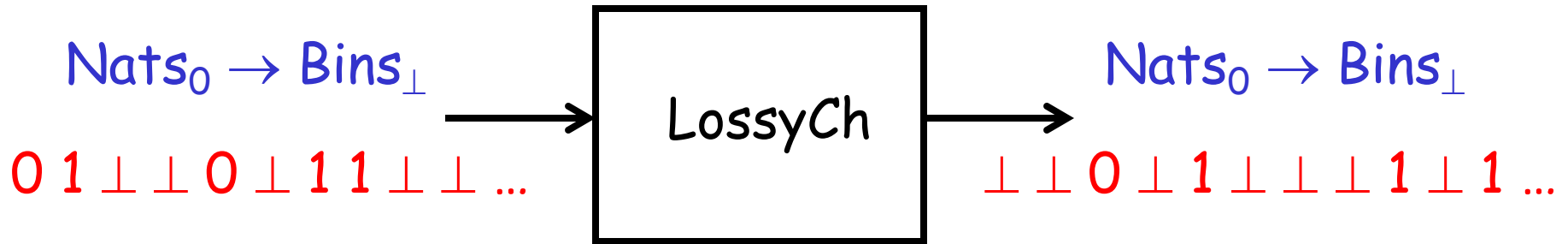
Finite state !

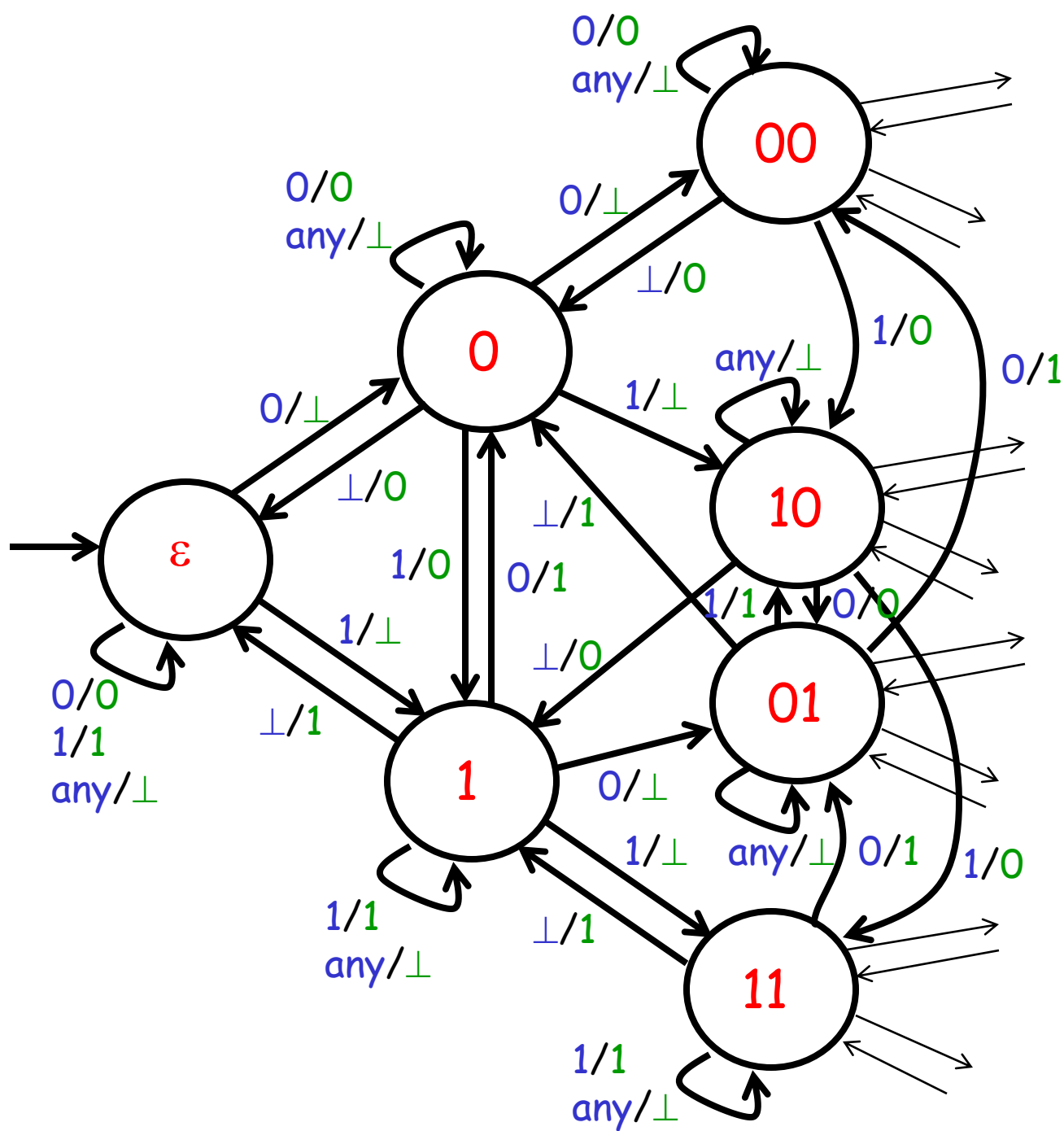


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any = { 0, 1, \perp }

Modeling Uncertainty: Lossy Channel





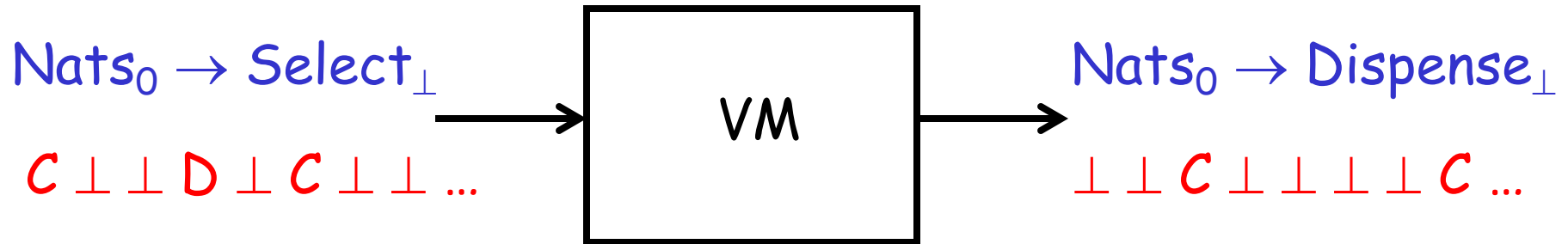
One possible run

Time	0	1	2	3	4	5	
Input	0	1	⊥	0	⊥	⊥	
Output	⊥	⊥	⊥	0	⊥	0	
State	ε	0	0	0	0	0	ε

Another possible run on the same input signal

Input	0	1	⊥	0	⊥	⊥	
Output	⊥	⊥	⊥	⊥	0	⊥	
State	ε	ε	ε	ε	0	ε	ε

Modeling Properties: Vending Machine

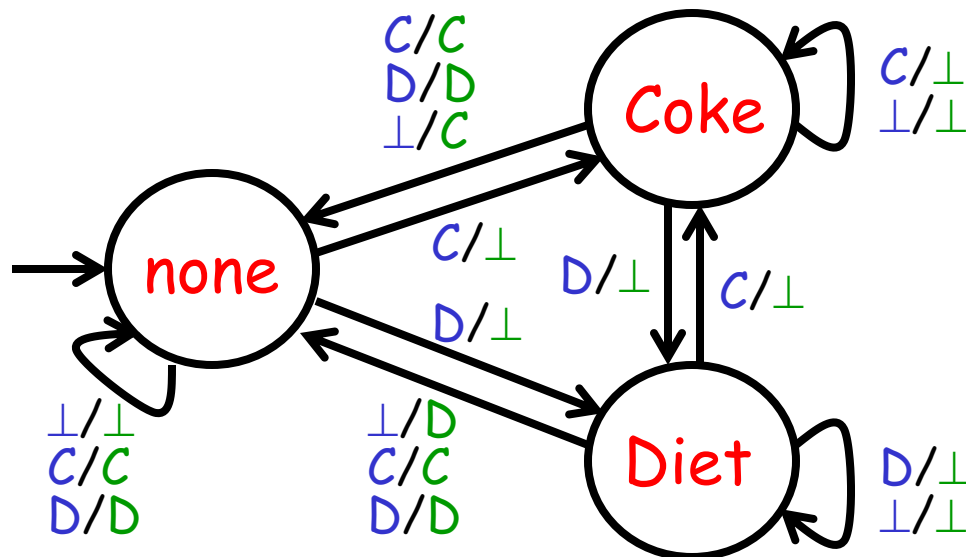


$\text{Select} = \text{Dispense} = \{ \text{Coke}, \text{Diet} \}$

"No-unrequested-soda" property:

Whenever the machine dispenses Coke, then the most recent request was for Coke;

whenever the machine dispenses Diet, then the most recent request was for Diet.



One possible run

Time	0	1	2	3	4	5	
Input	C	⊥	⊥	⊥	D	⊥	
Output	⊥	⊥	⊥	C	⊥	D	
State	n	C	C	C	n	D	n

Another possible run on the same input signal

Input	C	⊥	⊥	⊥	D	⊥	
Output	⊥	⊥	⊥	⊥	⊥	D	
State	n	C	C	C	C	D	n

Deterministic Reactive System:

for every input signal, there is **exactly one** output signal.

Nondeterministic Reactive System:

for every input signal, there is **one or more** output signals.

Deterministic Reactive System : function

$\text{DetSys} : [\text{Time} \rightarrow \text{Inputs}] \rightarrow [\text{Time} \rightarrow \text{Outputs}]$

Nondeterministic Reactive System : relation

$\text{NondetSys} \subseteq [\text{Time} \rightarrow \text{Inputs}] \times [\text{Time} \rightarrow \text{Outputs}]$

such that $\forall x \in [\text{Time} \rightarrow \text{Inputs}],$
 $\exists y \in [\text{Time} \rightarrow \text{Outputs}], (x,y) \in \text{NondetSys}$

Every pair $(x,y) \in \text{NondetSys}$ is called a
behavior

of the nondeterministic reactive system NondetSys .

S1 is a more detailed
description of S2;

S2 is an abstraction or
property of S1.

System S1 **refines** system S2

iff

1. Time [S1] = Time [S2] ,
2. Inputs [S1] = Inputs [S2] ,
3. Outputs [S1] = Outputs [S2] ,
4. Behaviors [S1] \subseteq Behaviors [S2] .

S1

refines

S2

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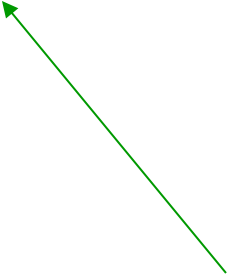
Vending machine

Fair coin

Arbitrary channel

No-unrequested-soda property

Nondeterministic coin



No output signal or heads, heads, heads, heads, ...
or tails, tails, tails, tails, ...

Systems $S1$ and $S2$ are **equivalent**
iff

1. $\text{Time}[S1] = \text{Time}[S2]$,
2. $\text{Inputs}[S1] = \text{Inputs}[S2]$,
3. $\text{Outputs}[S1] = \text{Outputs}[S2]$,
4. $\text{Behaviors}[S1] = \text{Behaviors}[S2]$.

Deterministic causal discrete-time reactive systems
can be implemented by
(deterministic) state machines.

Nondeterministic causal discrete-time reactive systems
can be implemented by
nondeterministic state machines.

Deterministic State Machine

Inputs

Outputs

States

$\text{initialState} \in \text{States}$

$\text{update} : \text{States} \times \text{Inputs} \rightarrow \text{States} \times \text{Outputs}$

Nondeterministic State Machine

Inputs

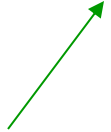
Outputs

States

possibleInitialStates \subseteq States

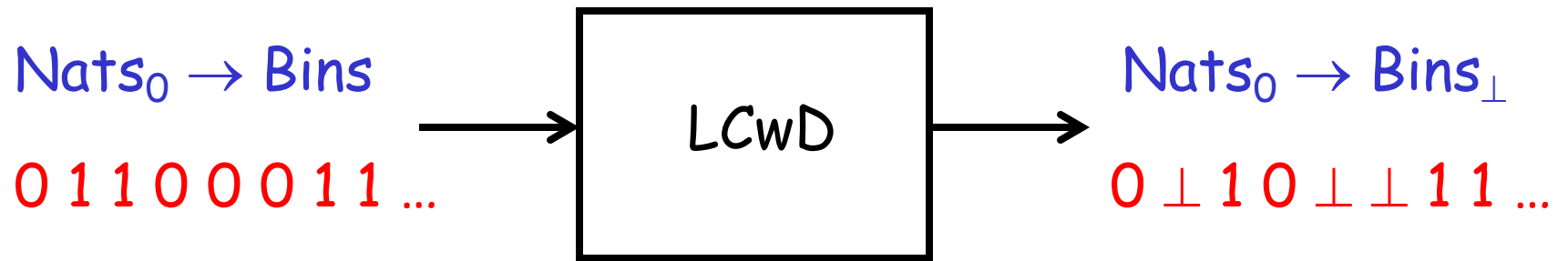
possibleUpdates :

States \times Inputs $\rightarrow P(\text{States} \times \text{Outputs}) \setminus \emptyset$

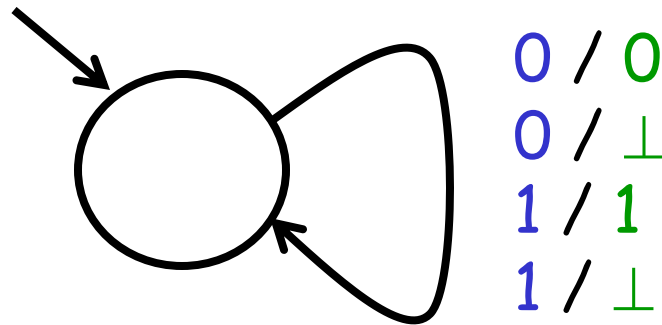
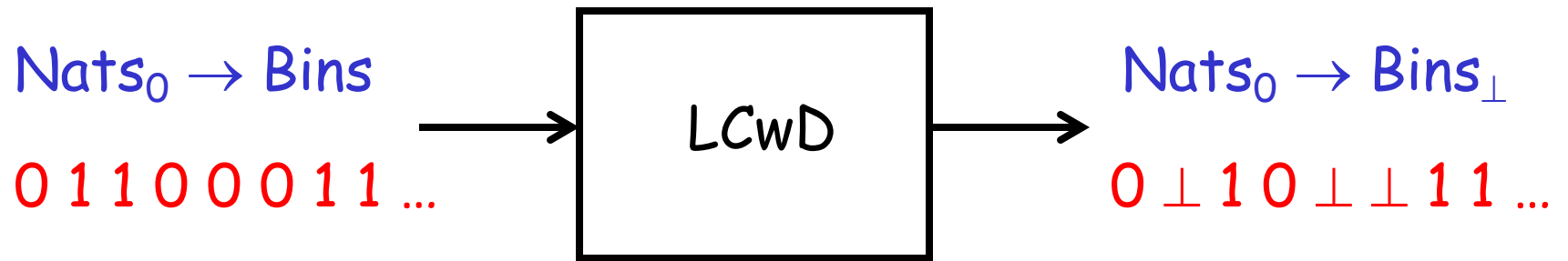


receptiveness (i.e., machine cannot prohibit an input)

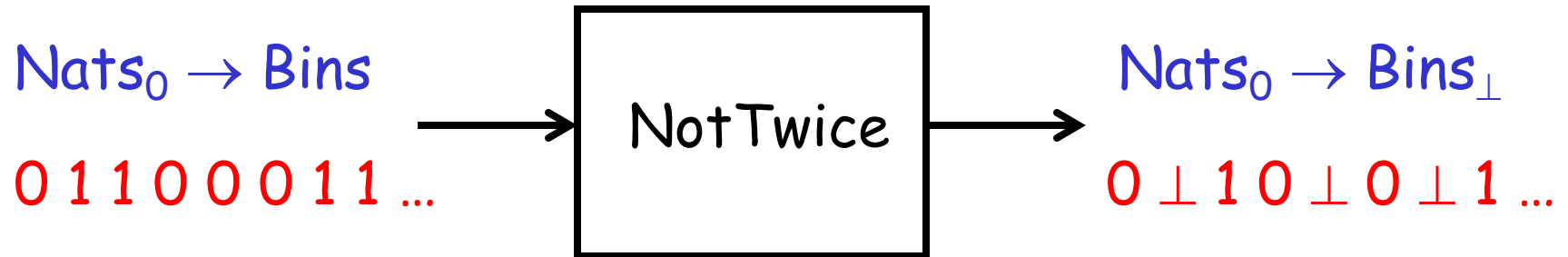
Lossy Channel without Delay



Lossy Channel without Delay



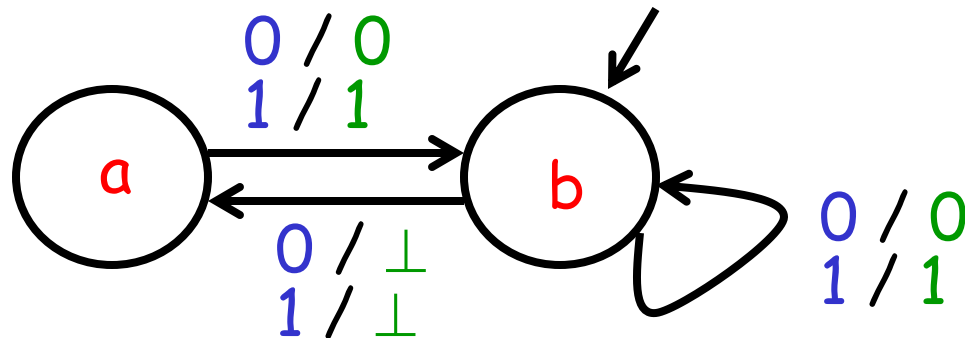
Channel that never drops two in a row



Channel that never drops two in a row

State between time $t-1$ and time t :

- a** the input at time $t-1$ was dropped
- b** the input at time $t-1$ was not dropped, or $t = 0$



Channel that never drops two in a row

Inputs = $\{0, 1\}$

Outputs = $\{0, 1, \perp\}$

States = $\{a, b\}$

possibleInitialStates = $\{b\}$

possibleUpdates (a, 0) = $\{(b, 0)\}$

possibleUpdates (a, 1) = $\{(b, 1)\}$

possibleUpdates (b, 0) = $\{(b, 0), (a, \perp)\}$

possibleUpdates (b, 1) = $\{(b, 1), (a, \perp)\}$

Deterministic state machine:

for every input stream, there is **exactly one** run.

Nondeterministic state machine:

for every input stream, there is **one or more** runs.

Every run generates an output stream, and
therefore every run gives rise to a behavior.