

Lectures on  
DIFFERENTIAL GEOMETRY AND TOPOLOGY

Lecture IV

★  $\mathbb{R}$ -forms

Let  $(V, K)$  be a vector space ( $K = \mathbb{R}$  or  $\mathbb{C}$ ),  $\dim_K V = n$

A  $\mathbb{R}$ -form (more precisely, algebraic  $\mathbb{R}$ -form) on  $V$  is a function  $\omega: \underbrace{V \times \dots \times V}_n \rightarrow K$

which is

1.  $\mathbb{R}$ -linear (i.e. linear in each argument)
2. skew-symmetric (alternating), that is

$$\begin{aligned} \omega(v_1, v_2, \dots, \alpha v_j^{(1)} + \beta v_j^{(2)}, \dots, v_n) &= \\ &= \alpha \cdot \omega(v_1, v_2, \dots, v_j^{(1)}, \dots, v_n) + \\ &\quad \beta \cdot \omega(v_1, v_2, v_j^{(2)}, \dots, v_n) \end{aligned} \quad j=1, 2, \dots, n$$

and

$$\omega(v_1, \dots, v_i, \dots, v_j, \dots, v_k) = -\omega(v_1, \dots, v_j, \dots, v_i, \dots, v_k) \quad i \neq j$$

Notice that  $\omega(v_1, \dots, v_i, \dots, v_i, \dots, v_k) = 0$

and that, in general

$$\omega(v_{i_1}, \dots, v_{i_k}) = \underbrace{(-1)^\sigma}_{\substack{\text{sign of the} \\ \text{permutation } \sigma}} \omega(v_1, \dots, v_k) \quad \left| \begin{array}{l} \sigma: (i_1 \ i_2 \ \dots \ i_k) \\ (-1)^\sigma = \pm 1 \\ +: \text{even permutation} \\ -: \text{odd permutation} \end{array} \right.$$

Recall:  $\sigma: (1 \dots n)$  is even if you go from

$(1, 2, \dots, n)$  to  $(i_1, \dots, i_k)$  performing an even

number of transpositions, i.e. switches  $(\dots \leftrightarrow \dots)$

[you may accomplish this in many ways, for a fixed permutation  $\sigma$ , however, the parity remains unaltered:

$$\begin{array}{l} \begin{pmatrix} 1 & 2 & 3 & 4 \\ 2 & 4 & 1 & 3 \end{pmatrix} \quad \begin{array}{l} \begin{array}{c} \leftrightarrow \\ (1 \ 2 \ 3 \ 4) \end{array} \rightarrow \begin{array}{c} \leftrightarrow \\ (2 \ 1 \ 3 \ 4) \end{array} \\ \rightarrow \begin{array}{c} \leftrightarrow \\ (2 \ 1 \ 4 \ 3) \end{array} \rightarrow \begin{array}{c} \leftrightarrow \\ (2 \ 4 \ 1 \ 3) \end{array} \end{array} \\ \text{3 switches:} \quad \text{parity: } -1 \quad \text{odd number of transposition} \end{array}$$

Alternatively:

$$\begin{array}{l} (1 \ 2 \ 3 \ 4) \rightarrow (1 \ 2 \ 4 \ 3) \rightarrow (2 \ 1 \ 4 \ 3) \\ \rightarrow (2 \ 4 \ 1 \ 3) \end{array}$$

3 switches: parity: -1

(notice that one may use in general just simple transpositions, i.e. exchanges of adjacent elements)

or, for instance

$$\begin{array}{l} (1 \ 2 \ 3 \ 4) \rightarrow (1 \ 2 \ 4 \ 3) \rightarrow (1 \ 4 \ 2 \ 3) \\ \rightarrow (4 \ 1 \ 2 \ 3) \rightarrow (4 \ 2 \ 1 \ 3) \rightarrow (2 \ 4 \ 1 \ 3) \\ \text{5 switches: parity: } -1 \end{array}$$

Notation:  $\Delta^k(V^*)$   
k-forms on  $V$

Actually  $\Delta^k(V^*) \subseteq (V^*)^{\otimes k}$   
vector subspace

\* Examples

(1) The determinant (of a square matrix)

$$\det : M_n(K) \ni A \longrightarrow K$$

$$\left( \begin{array}{ccc} \text{⌋} & \text{⌋} & \dots & \text{⌋} \\ C_1 & C_2 & & C_n \end{array} \right)$$

i.e.  $A$  is  
(looked upon as  
a matrix of columns)

1 & 2 hold  
and, moreover

$$3. \det(I_n) = 1$$

↑  
identity  
 $n \times n$  matrix

\* Geometric interpretation: volume of a "hyperparallelepiped" formed with the columns of  $A$  (or rows...)

(2) Flux of a (constant, for the time being) field  $\underline{F}$  through a surface: to fix ideas, a space parallelogram formed with two l.o.i. vectors  $\underline{a}, \underline{b}$ .

"mixed product"

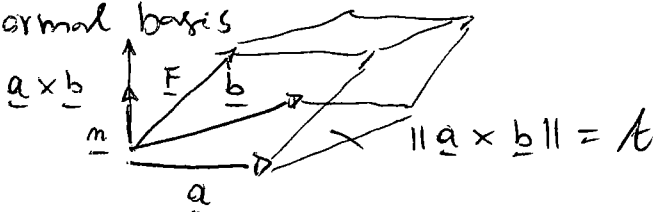
$$\Phi_F : (\underline{a}, \underline{b}) \longmapsto \langle \underline{F}, \underline{a} \times \underline{b} \rangle_n$$

Standard scalar product  
↑  
vector product

flux 2-form  
build-up columns with  
the components  
of  $\underline{F}, \underline{a}, \underline{b}$  w.r. to  
an orthonormal basis

$$\det \begin{pmatrix} \underline{F} \\ \underline{a} \\ \underline{b} \end{pmatrix}$$

in  
geometric  
vector space



$$\Phi_F = \langle \underline{F}, \underline{n} \rangle A$$

$$= \langle \underline{F}, \underline{A} \rangle$$

$A \underline{n}$ : area vector

\* Theorem  $\dim \Lambda^R(V^*) = \begin{cases} \binom{n}{R} & \text{if } 0 \leq R \leq n \\ 0 & \text{if } R > n \end{cases}$   
 Note that  $\Lambda^1(V^*) = V^*$   
 and  $\dim \Lambda^k(V^*) = \dim \Lambda^{n-k}(V^*)$   
 ( $\Lambda^R(V^*) = \{0\}$  for  $R > n$ )

Proof (sketch). Let  $e = (e_1, \dots, e_n)$  be a basis of  $V$ .

a  $R$ -form  $\omega$  is completely determined, in view of  $R$ -linearity and skew-symmetry, by the values

$$\omega(e_{i_1}, e_{i_2}, \dots, e_{i_R}), \quad i_1 < i_2 < \dots < i_R$$

[notice that, permuting any two entries in  $\bullet$ , one gets  $\pm \omega(e_{i_1}, \dots, e_{i_R})$ ]

Therefore, the number of "free parameters" is given by combinations of  $n$  objects in  $R$  places (the arguments of the  $R$ -form), that is, by

the binomial coefficient  $\binom{n}{R}$ ,

$$\text{if } 0 \leq R \leq n \quad (\Lambda^0(V^*) = K)$$

notice that if  $R > n$ , in the allocation, at least a basis vector is being inserted twice, so by skew-symmetry one gets 0.

- try one gets 0.

A basis for  $\Lambda^R(V^*)$  is given as follows ( $R \leq n$ )

Let  $I = (i_1, \dots, i_R)$ ,  $i_1 < i_2 < \dots < i_R$  a multi-index, set

$$e_I^* (e_{j_1}, \dots, e_{j_R}) = \begin{cases} \pm 1 & \text{if } J \text{ is a permutation of } I \\ & \text{according to parity} \\ 0 & \text{otherwise} \end{cases}$$

Then  $\omega = \sum_I \omega(e_{i_1}, \dots, e_{i_R}) e_I^*$ , and moreover

the  $e_I^*$  are linearly independent.

We shall obtain a more explicit description of  $e_I^*$  later on

\* Exterior (or wedge) product of forms

use the preceding notation

Let  $\omega^R$  be a  $R$ -form  
 $\omega^l$  be an  $l$ -form

The wedge product of  $\omega^R$  and  $\omega^l$ , denoted by exterior product in this order

$\omega^R \wedge \omega^l$  is a  $(R+l)$ -form defined as follows:

$$(\omega^R \wedge \omega^l)(v_1, \dots, v_{R+l}) := \frac{1}{R!l!} \sum_{\nu} (-1)^\nu \omega^R(v_{i_1}, \dots, v_{i_R}) \omega^l(v_{i_{R+1}}, \dots, v_{i_{R+l}})$$

$\left( \begin{matrix} 1 & 2 & \dots & R+l \\ i_1 & i_2 & \dots & i_{R+l} \end{matrix} \right)$   
 (sum over all permutations)  
 $(-1)^\nu$  parity of  $\nu$

take any permutation of  $v_1, \dots, v_{R+l}$  distribute the arguments in the manner indicated

other conventions are possible

Properties: 1. graded commutativity

$$\omega^R \wedge \omega^l = (-1)^{Rl} \omega^l \wedge \omega^R$$

2. distributivity.  $(\alpha \omega_1^R + \beta \omega_2^R) \wedge \omega^l =$   
 $= \alpha \omega_1^R \wedge \omega^l + \beta \omega_2^R \wedge \omega^l$

3. associativity:  $(\omega^R \wedge \omega^l) \wedge \omega^P = \omega^R \wedge (\omega^l \wedge \omega^P)$   
 $\equiv \omega^R \wedge \omega^l \wedge \omega^P$  (no ambiguity arising)

Let us check 1.

notice that in order to go from

$$(i_1 \dots i_k, i_{k+1} \dots i_{k+l}) \text{ to } (i_{k+1} \dots i_{k+l}, i_1 \dots i_k),$$

one needs  $kl$  (simple) transpositions. Also,

$$(i_1 \dots i_k, i_{k+1} \dots i_{k+l})$$

each element is moved to the final position by means of  $kl$  transpositions, and  $l$  elements intervene.

see box the parity of

$$(\diamond) \begin{pmatrix} 1 & 2 & \dots & k+l \\ i_{k+1} & i_{k+2} & i_{k+l} & i_1, i_2, \dots, i_k \end{pmatrix}$$

$$\text{is } (-1)^{\sum} (-1)^{kl}$$

$$\text{and } (-1)^{\sum} = (-1)^{\sum} (-1)^{2kl}$$

$$\left[ \begin{array}{ccc} (1 \ 2 \ \dots \ k+l) & \xrightarrow{(-1)^{\sum}} & (i_1, i_2 \ \dots \ i_{k+l}) \\ & & \xrightarrow{(-1)^{kl}} & (i_{k+1}, i_{k+2} \ \dots \ i_1 \ \dots \ i_k) \end{array} \right]$$

We are now prepared for the actual computation:

$$(\omega^k \wedge \omega^l)(v_1, \dots, v_{k+l}) = \frac{1}{k!l!} \sum_{\sum} (-1)^{\sum} \omega^k(v_{i_1} \dots v_{i_k}) \omega^l(v_{i_{k+1}} \dots v_{i_{k+l}})$$

$$= \frac{1}{k!l!} \sum_{\sum} (-1)^{\sum} \omega^l(v_{i_{k+1}} \dots v_{i_{k+l}}) \omega^k(v_{i_1} \dots v_{i_k})$$

$$= (-1)^{kl} \frac{1}{k!l!} \sum_{\sum} \underbrace{(-1)^{\sum} (-1)^{kl}}_{\substack{\text{parity of } (\diamond) \\ \text{sum over all permutations}}} \omega^l(v_{i_{k+1}} \dots v_{i_{k+l}}) \omega^k(v_{i_1} \dots v_{i_k})$$

$$= (-1)^{kl} (\omega^l \wedge \omega^k)(v_1 \dots v_{k+l})$$

Let us check associativity.

It is enough to establish it for monomials of the form  $e_{i_1}^* \wedge e_{i_2}^* \dots \wedge e_{i_n}^*$ , therefore, by skew-symmetry and induction, it suffices to check, to fix ideas,

$$(e_1^* \wedge e_2^*) \wedge e_3^* = e_1^* \wedge (e_2^* \wedge e_3^*),$$

and, by multilinearity & skew-symmetry again, it is enough to verify that, if both sides are evaluated on  $(e_1, e_2, e_3)$ , we get the same result (we should find 1)

So compute:

$$\begin{aligned} & \left( (e_1^* \wedge e_2^*) \wedge e_3^* \right) (e_1, e_2, e_3) = \underbrace{-1}_{-1} \underbrace{1}_{1} \\ & \frac{1}{2} \left[ \underbrace{(e_1^* \wedge e_2^*)}_{1} (e_1, e_2) \underbrace{e_3^*}_{1} (e_3) - \underbrace{(e_1^* \wedge e_2^*)}_{-1} (e_2, e_1) \underbrace{e_3^*}_{1} (e_3) \right] \\ & \quad + \text{other 4 summands equal to 0:} \\ & \quad e_3^* \text{ must in fact act on } e_1 \text{ or } e_2, \text{ yielding 0} \end{aligned}$$

note

Let us evaluate  $(e_1^* \wedge e_2^*)(e_1, e_2)$  directly:

$$\begin{aligned} (e_1^* \wedge e_2^*)(e_1, e_2) &= \underbrace{e_1^*(e_1)}_{1} \underbrace{e_2^*(e_2)}_{1} - \underbrace{e_1^*(e_2)}_{0} \underbrace{e_2^*(e_1)}_{0} \\ &= +1. \end{aligned}$$

Therefore  $\left( (e_1^* \wedge e_2^*) \wedge e_3^* \right) (e_1, e_2, e_3) = +1$

The r.h.s. is also easily seen to be +1 as well.

In order to grasp the geometrical meaning of  $\wedge$  (crucial for the sequel), let us compute (exercise)  $\text{in } \mathbb{R}^2$

$$(e_1^* \wedge e_2^*)(v_1, v_2) = \begin{matrix} v_1 = \alpha_1 e_1 + \alpha_2 e_2 \\ v_2 = \beta_1 e_1 + \beta_2 e_2 \end{matrix}$$

bilinearity

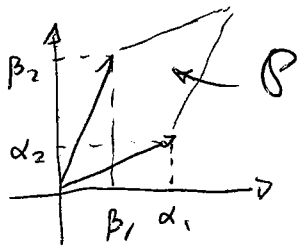
$$\alpha_1 \beta_1 \underbrace{(e_1^* \wedge e_2^*)(e_1, e_1)}_{=0} + \alpha_1 \beta_2 \underbrace{(e_1^* \wedge e_2^*)(e_1, e_2)}_{=+1}$$

equal arguments

$$+ \alpha_2 \beta_1 \underbrace{(e_1^* \wedge e_2^*)(e_2, e_1)}_{=-1} + \alpha_2 \beta_2 \underbrace{(e_1^* \wedge e_2^*)(e_2, e_2)}_{=0}$$

$$= \alpha_1 \beta_2 - \alpha_2 \beta_1 = \begin{vmatrix} \alpha_1 & \beta_1 \\ \alpha_2 & \beta_2 \end{vmatrix}$$

$v_1 \quad v_2$



= oriented area of  $P$   
i.e., with sign

$\begin{matrix} \gamma_1 e_1 & \gamma_2 e_1 & \gamma_3 e_1 \\ \parallel & \parallel & \parallel \\ \gamma_1 e_1 & \gamma_2 e_1 & \gamma_3 e_1 \end{matrix}$

★ Check that, in  $\mathbb{R}^3$ ,  $(e_1^* \wedge e_2^* \wedge e_3^*)(v_1, v_2, v_3)$

$$= \dots = \begin{vmatrix} \alpha_1 & \beta_1 & \gamma_1 \\ \alpha_2 & \beta_2 & \gamma_2 \\ \alpha_3 & \beta_3 & \gamma_3 \end{vmatrix} \quad \text{oriented volume of the obvious parallelepiped...}$$