

Lectures on

DIFFERENTIAL GEOMETRY AND TOPOLOGY

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Lecture XIV

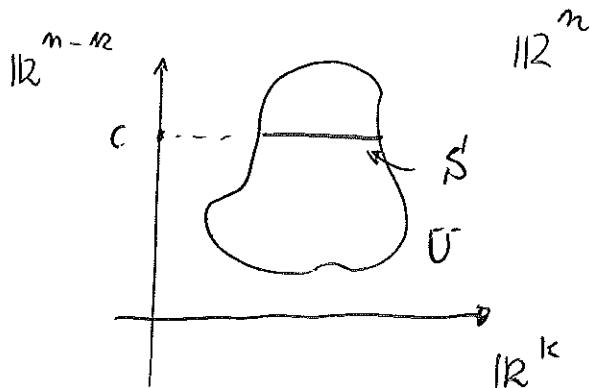
* R-slices

The sets of the form

$$S^l = \left\{ (\alpha^1, \dots, \alpha^k, \alpha^{k+1}, \dots, \alpha^n) \in U \mid \alpha^{k+1} = c^{k+1}, \dots, \alpha^n = c^n \right\}$$

open set in \mathbb{R}^n
 R fixed

are called R-slices of U



* Extension of the fundamental theorems of analysis in several variables to manifolds.

* The inverse function theorem

$$\varphi: X \rightarrow Y \quad \text{if } \varphi \text{ smooth}$$

$$\dim X = \dim Y = n$$

Let $\varphi_x|_{x_0}: T_{x_0} X \rightarrow T_{y_0} Y$ be an isomorphism.

Then $\exists U_0 \ni x_0$ such that
neighborhood
of x_0

$$\psi|_{U_0} : U_0 \rightarrow \psi(U_0)$$

is a diffeomorphism

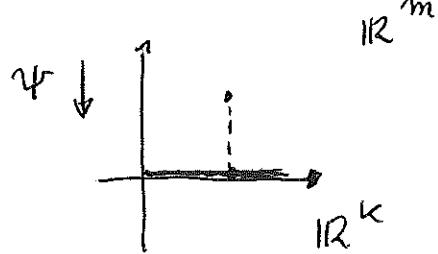
In coordinates, the proof reduces to the standard one,
via the contraction lemma (Banach-Caccioppoli theorem)

* The rank theorem

Let $\psi : M \rightarrow N$ ($\dim M = m$, $\dim N = n$)
be smooth, with constant rank k $1 \leq k \leq m$. Then
 $\forall p \in M$, there exist coordinates $(x^1 \dots x^m)$ centred
at p and $(y^1 \dots y^n)$ centred at $\psi(p)$ such
that

$$\psi(x^1 \dots x^k, x^{k+1} \dots x^m) = (x^1 \dots x^k, 0, \dots, 0) \quad / \quad k \leq \min(m, n)$$

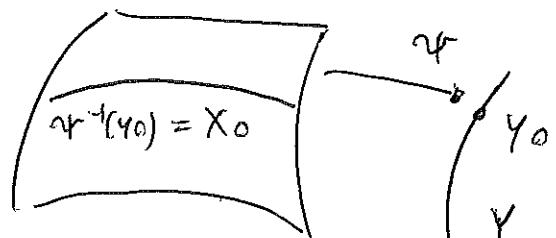
a slice in \mathbb{R}^n



* The implicit function theorem

Let $\psi : X \rightarrow Y$ smooth, $\dim X = n >$
 $\dim Y = m$

If $y_0 \in Y$ and $X_0 = \psi^{-1}(y_0) = \{x \in X / \psi(x) = y_0\}$



Assume that

$$\psi_*|_{x_0} : T_{x_0} X \rightarrow T_{\psi(x_0)} Y$$

ψ is surjective $\forall x \in X_0$.

That is, ψ is submersive ($\forall x \in X_0$).

Then X_0 is a manifold (equipped with the relative topology inherited from X), and $X_0 \hookrightarrow X$
 Conclusion) is smooth. Moreover $\dim X_0 = \dim X - \dim Y$
 X_0 : level manifold (of ψ)
 varieties de levée
 $= n - m$.

Proof. (Sketch) Let $V \ni y_0$ a coordinate neighbourhood
 (of y_0) with local coordinates $(y^1 \dots y^m)$. Let $x_0 \in X_0$
 and $U \ni x_0$ (coord. neighbourhood), with local
 coordinates $(x^1 \dots x^n)$ centred at x_0 ($x^i(x_0) = 0, i=1 \dots n$).
 Since $\psi_*|_{x_0}$ is surjective, the Jacobian matrix

$$\left(\frac{\partial}{\partial x^j} (\psi^{-1}(y^i)) \Big|_{x_0} \right)_{\substack{i=1 \dots m \\ j=1 \dots n}}$$

has rank m , so, up to a coordinate relabelling
 one can assume it to be of the form

$$(\ast \mid J)$$

\uparrow
 $m \times m$, non singular

Define $\tilde{\psi} : U \rightarrow \mathbb{R}^{n-m} \times V$ in the following
 manner:

$$\tilde{\psi}(x) = (x^1(x) \dots x^{n-m}(x), \psi(x))$$

$$\Rightarrow \tilde{\psi}_*|_{x_0} \sim \begin{pmatrix} I_{n-m} & 0 \\ \ast & J \end{pmatrix}$$

examples on pages 6, 7

which is an isomorphism. Therefore, by virtue of the inverse function theorem, $\exists U_0 \ni x_0$ such that $\tilde{\psi}|_{U_0}$ is injective, $\tilde{\psi}(U_0)$ is open in $\mathbb{R}^{n-m} \times V$ and $\tilde{\psi}^{-1}: \tilde{\psi}(U_0) \rightarrow U_0$ is smooth.

Without loss of generality (w.l.o.g.), $\tilde{\psi}(U_0)$ can be taken of the form $W_0 \times V_0 \cong$
 open hyperparallelopipedes $\xrightarrow{\Psi_0} \begin{array}{c} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{array} \xrightarrow{y_0} \begin{array}{c} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{array} \mathbb{R}^{n-m}$

Open sets of this type yield a basis for the topology of $\mathbb{R}^{n-m} \times V$.

Now $\tilde{\psi}^{-1}(W_0 \times \{y_0\}) = X_0 \cap U_0$.

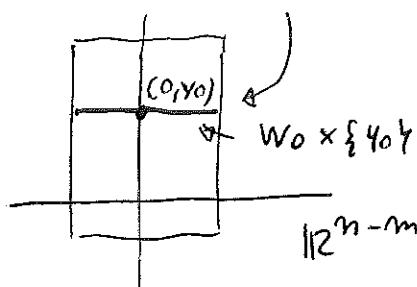
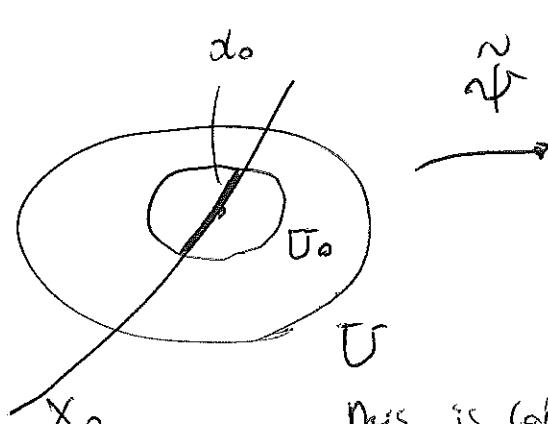
Since $\tilde{\psi}|_{U_0}$ is a homeomorphism, the map

$$\tilde{\psi}|_{X_0 \cap U_0} : X_0 \cap U_0 \xrightarrow{\text{homeom.}} W_0 \times \{y_0\} \subset \mathbb{R}^{n-m}$$

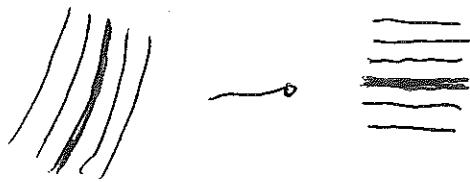
is a coordinate system in a neighbourhood

of x_0

a $(n-m)$ -slice in \mathbb{R}^n



This is called a $(n-m)$ -slice chart

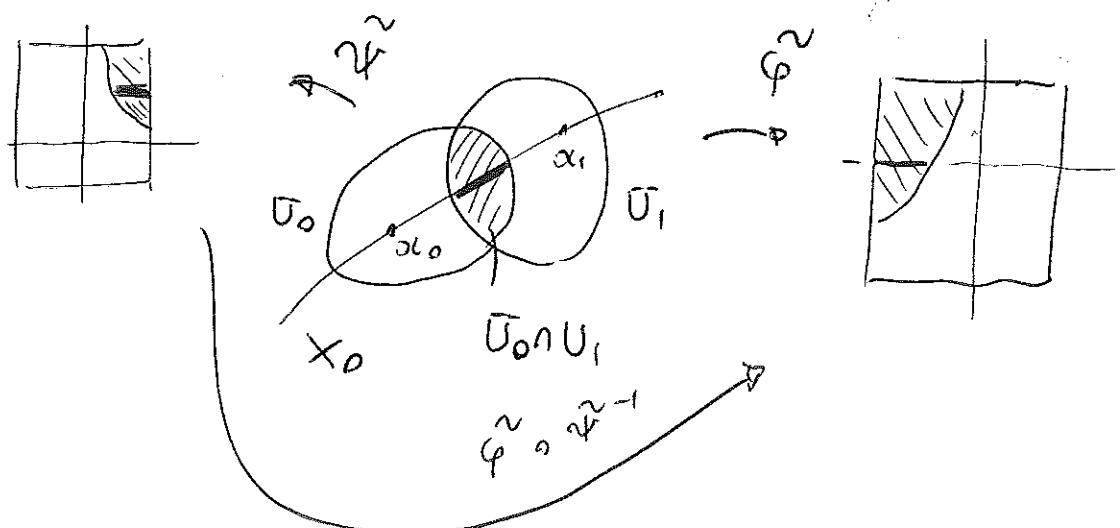


level sets of $\tilde{\psi}$

One is left with checking the behaviour on non empty intersections

$$\tilde{\psi} : U_0 \rightarrow W_0 \times V_0$$

$$\tilde{\varphi} : U_1 \rightarrow W_1 \times V_1$$



$\tilde{\varphi} \circ \tilde{\psi}^{-1} |_{\tilde{\psi}(U_0 \cap U_1)}$ is C^∞ , and so is

$$\begin{aligned} \tilde{\varphi} \circ \tilde{\psi}^{-1} &: \tilde{\psi}(x_0 \cap U_0 \cap U_1) \rightarrow \\ &\quad \tilde{\varphi}(x_0 \cap U_0 \cap U_1) \\ &(\tilde{\psi}(U_0 \cap U_1) \cap \mathbb{R}^{n-m}) \times \{y_0\} \end{aligned}$$

(The same being true for $\tilde{\psi} \circ \tilde{\varphi}^{-1}$),

and this yields the desired conclusion.

* Dini's Theory revisited

via the inverse function theorem

explicit examples

* curves in \mathbb{R}^2

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}$$

$$f(x, y) = 0$$

$$P_0: (x_0, y_0)$$

$$f(P_0) = 0$$

(or more generally $f(x, y) = c$)

$$\frac{\partial f}{\partial y}(P_0) \neq 0 \Rightarrow \text{loc. } \exists! \quad y(x), \quad y_0 = y(x_0)$$

with $f(x, y(x)) \equiv 0 \quad \forall x$ (in a suitable interval)

Define $\downarrow \mathbb{R}^2$

$x \quad y$

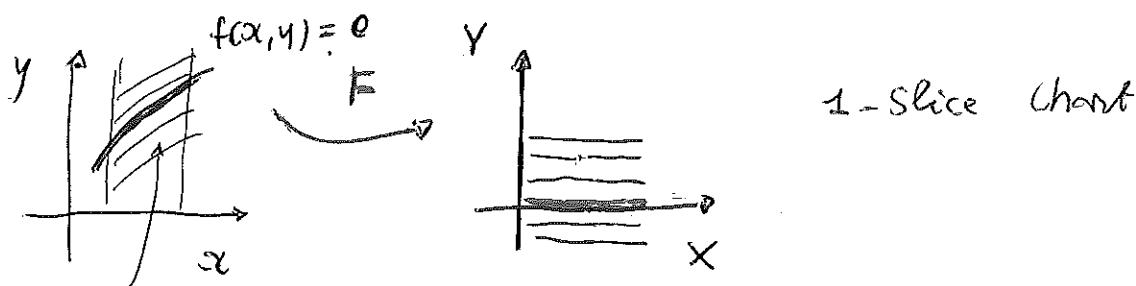
$$F: (x, y) \longmapsto (x, f(x, y)) \in \mathbb{R}^2$$

$$F: \begin{cases} x = x \\ y = f(x, y) \end{cases} \quad \begin{aligned} dx &= dx \\ dy &= f_x dx + f_y dy \end{aligned}$$

$$F_x: \begin{pmatrix} 1 & 0 \\ f_x & f_y \end{pmatrix} \quad f_y \neq 0 \Rightarrow$$

F_x^{-1} isomorphism

\Rightarrow locally F is a diffeom.



level sets are "rectified"

* Surfaces in \mathbb{R}^3

$$f: \mathbb{R}^3 \rightarrow \mathbb{R}$$

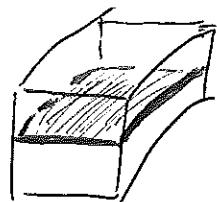
$$f(x, y, z) = 0 \quad f_z' \neq 0$$

$$f(x_0, y_0, z_0) = 0$$

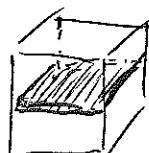
$$F: \begin{matrix} (x, y, z) \mapsto \\ \mathbb{R}^3 \end{matrix} \begin{matrix} (x, y, f(x, y, z)) \\ X \ Y \ Z \end{matrix} \subset \mathbb{R}^3$$

$$F_* = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ f_x & f_y & f_z \end{pmatrix}$$

$f_z' \neq 0 \Rightarrow F_*^0$ isomorphism
 \Rightarrow locally F is a diffeom.



$$\xrightarrow{F}$$



2-slice in \mathbb{R}^3

2-slice chart

$$\xrightarrow{F}$$

* Curves in \mathbb{R}^3

$$F: \mathbb{R}^3 \rightarrow \mathbb{R}^3$$

$$\begin{cases} f=0 \\ g=0 \end{cases}$$

$$(x, y, z) \mapsto (x, f(x, y, z), g(x, y, z))$$

$$\begin{matrix} || & || & || \\ X & Y & Z \end{matrix}$$

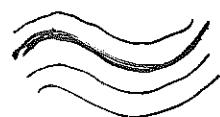
$$\boxed{\begin{array}{c} \mathbb{R}^3 \xrightarrow{(f, g)} \mathbb{R}^2 \\ (x, y, z) \xrightarrow{(f, g)} (0, 0) \end{array}}$$

$$F_* = \begin{pmatrix} 1 & 0 & 0 \\ f_x & f_y & f_z \\ g_x & g_y & g_z \end{pmatrix}$$

$$\frac{\partial(f, g)}{\partial(y, z)}(P_0) \neq 0$$

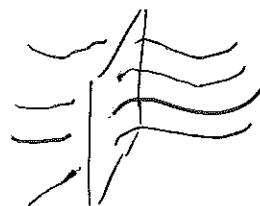
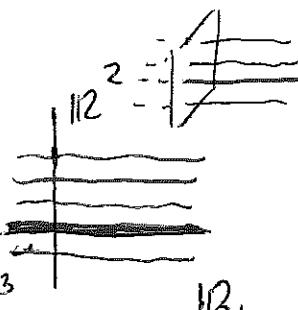
F_*^0 isom.

$\Rightarrow F$ local diffeom.



$$\xrightarrow{F}$$

1-slice in \mathbb{R}^3



Schaarwichtige Immersion

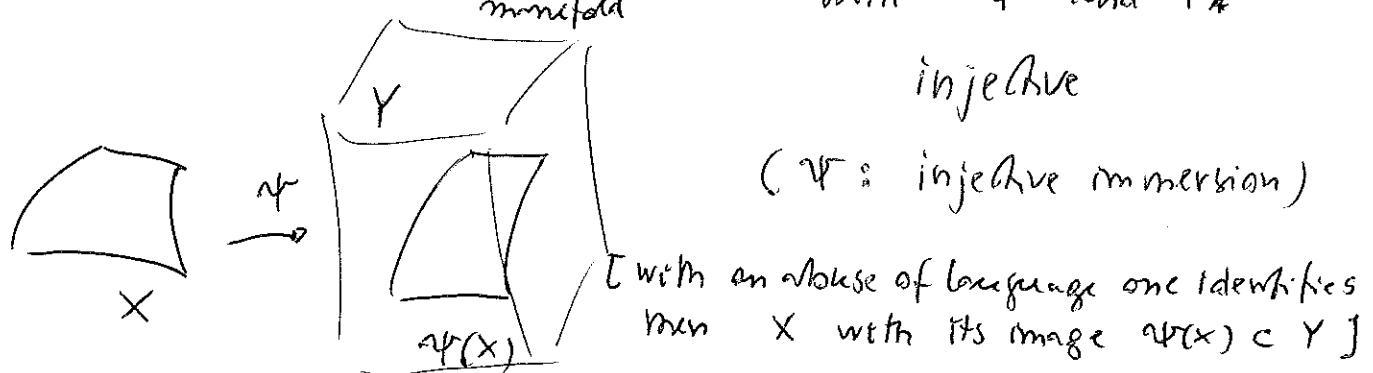
Def. (i) An ^{smooth} immersed submanifold of a manifold Y is a pair (X, ψ) , $\psi : X \rightarrow Y$, smooth

^{smooth}
manifold

with ψ and ψ_x

injective

(ψ : injective immersion)



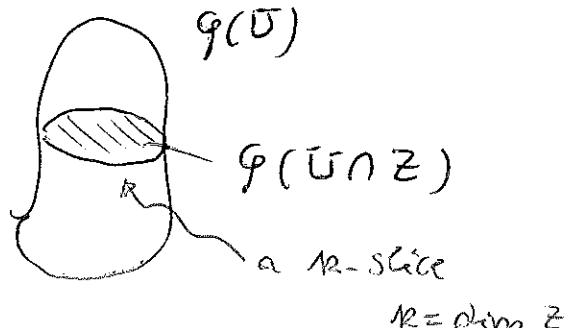
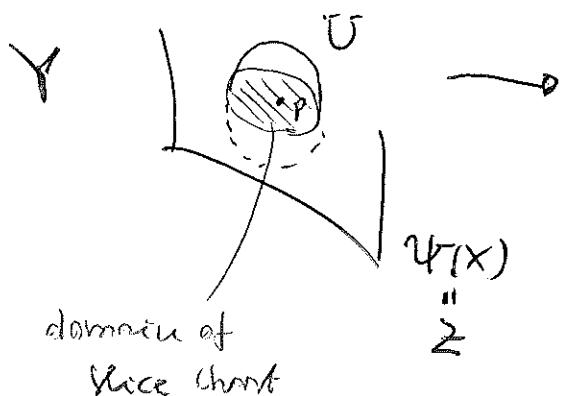
(ii) One has an embedding if, in addition to (i),
inclusion

$\psi : X \rightarrow \psi(X)$ is a homeomorphism

(with $\psi(X)$ equipped with the relative topology induced from Y)

~~At~~ Let us check that, if ψ is an embedding, then $\psi(X)$ is a submanifold of Y in the following sense:

Every point of $\psi(X)$ admits a coordinate neighbourhood $U \subset Y$ such that $\psi(X) \cap U$ is the domain of a slice-chart



Remark. The level submanifolds previously discussed are indeed submanifolds of X in the above sense.

Proof. Let $\alpha \in X$. Since an embedding has constant rank, by the rank theorem one can find local coordinate systems centred at α and $\psi(\alpha)$, respectively, with

$$\text{abuse of notation } \rightsquigarrow \psi: (x^1 \dots x^k) \xrightarrow{\quad U \quad} (x^1 \dots x^k, 0 \dots 0) \quad \begin{matrix} \downarrow V \\ \dim X \end{matrix} \quad \begin{matrix} \downarrow V \\ \dim Y - \dim X \end{matrix}$$

upon possible restriction of V , $\psi(U)$ becomes a slice in Y . Now $\psi(U)$ is open in $\psi(X)$

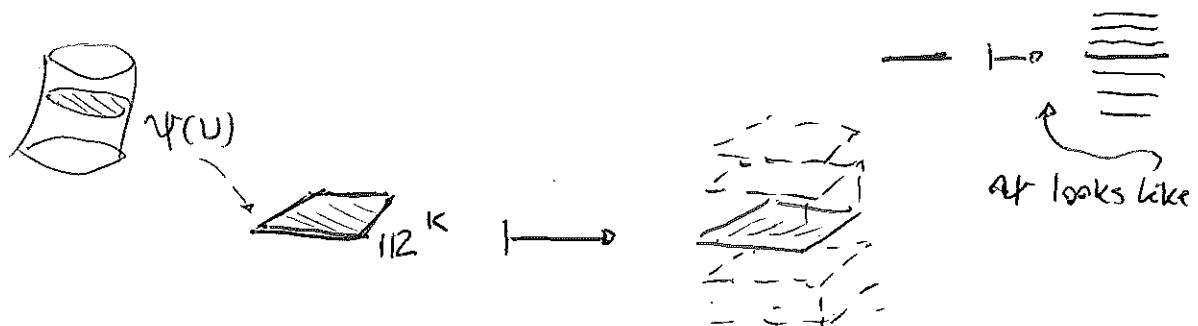
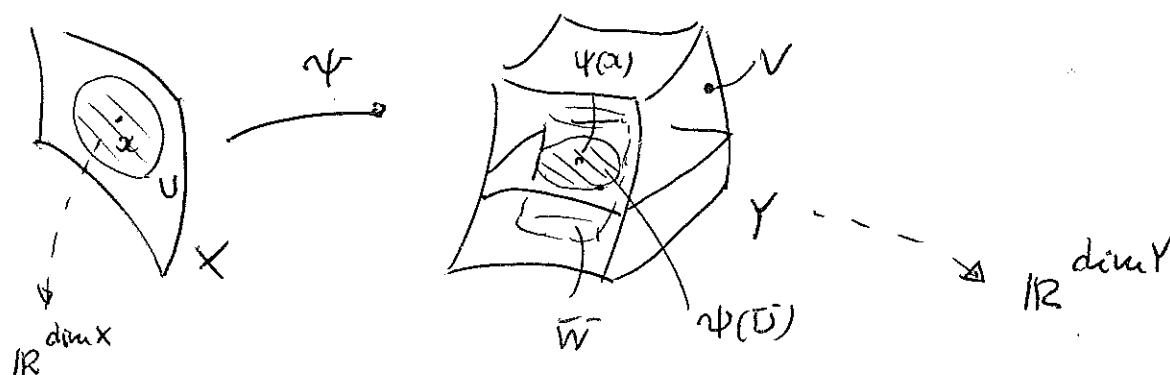
(it is a homeomorphism onto $\psi(X)$) $\Rightarrow \exists W \subset Y$

such that $\psi(U) = \bar{W} \cap \psi(X)$

!
this
is
the
crucial
point

Let $\tilde{V} = V \cap W$. One produces a slice chart

such that $\tilde{V} \cap \psi(X) = \tilde{V} \cap \psi(U)$ is a slice in \tilde{V}



Notice that if X is compact, π^* is automatically a homeomorphism onto $\pi(X)$ (since $\pi(X)$ is Hausdorff and π^* is injective)

In any case, in view of Dini's theorem,
 π injective + π^* injective $\Rightarrow \pi^*$ homeomorphism (locally)

i.e. an injective immersion is locally an embedding

* Summary. F_* (differential, or push-forward)

* crucial tools slogan " F_* behaves locally like F "

| inverse function theorem |

\downarrow

- rank theorem
- implicit function theorem

important case: surjective submersions

$$F: M \rightarrow N$$

rank of F at $p \in M \equiv$ rank of $F_*: T_p M \rightarrow T_{F(p)} N$
 if this does not vary with p , we say F of constant rank

F : submersion : F_* surjective $\forall p \in M$ rank
 $r(F) = \dim N$

F : immersion : F_* injective $r(F) = \dim M$

F : embedding : F immersion + F homeomorphism
 onto $F(M)$

equivalently :

"topological embedding"

F injective

F_* injective

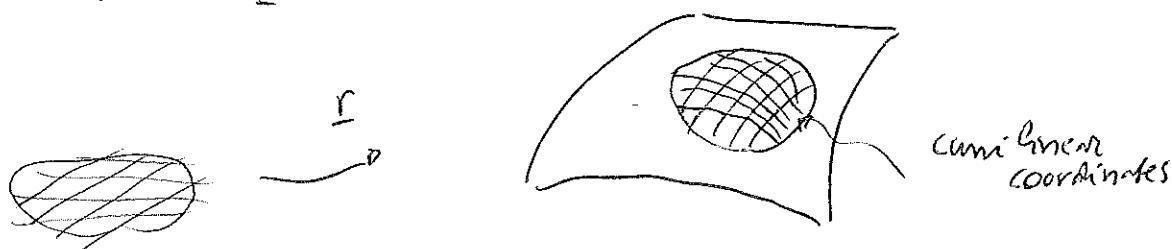
$F: M \rightarrow F(M)$ homeomorphism

equipped with the

relative topology inherited from N

* Notice that we obviously recover the elementary treatment of (parametric) surfaces. Remember:

1. $\underline{r} = \underline{r}(u, v)$ \mathcal{C}^k $(u, v) \in \mathcal{U} \subset \mathbb{R}^2$
2. \underline{r} injective
3. $\underline{r}_u \times \underline{r}_v \neq 0$



|| $\underline{r} = \underline{r}(u, v)$. fulfilling 1 - 3 is in fact an injective immersion (and locally an embedding)

What was not mentioned upon in the geometry course was invariance of conditions 1 - 3 under

diffeomorphisms of \mathcal{U} : $g: \begin{cases} u' = u'(u, v) \\ v' = v'(u, v) \end{cases}$



$$R = r \circ g^{-1}$$

$$R(u', v') = r(u'(u', v'), v'(u', v'))$$

1 & 2 are clear for R , and 3 is simple as well:

$$R_{u'} \times R_{v'} = \left(\frac{\partial u}{\partial u'} \frac{\partial v}{\partial v'} - \frac{\partial u}{\partial v'} \frac{\partial v}{\partial u'} \right) \underline{r}_u \times \underline{r}_v$$

$$\frac{\partial R}{\partial u'} = \frac{\partial r}{\partial u} \frac{\partial u}{\partial u'} + \frac{\partial r}{\partial v} \frac{\partial v}{\partial u'} \quad \left. \frac{\partial(u, v)}{\partial(u', v')} \right| \neq 0$$

$$\frac{\partial R}{\partial v'} = \frac{\partial r}{\partial u} \frac{\partial u}{\partial v'} + \frac{\partial r}{\partial v} \frac{\partial v}{\partial v'} \quad \left. \begin{vmatrix} u_{u'} & u_{v'} \\ v_{u'} & v_{v'} \end{vmatrix} \right|$$

* Examples

1. $F : \mathbb{R} \rightarrow \mathbb{R}$

$$x \mapsto e^x \quad \text{Im}(F) = \mathbb{R}^+$$

is a submersion which is not surjective

$$F_*|_x = e^x \quad (de^x = e^x dx)$$

$$e^x : T_x \mathbb{R} \rightarrow T_{e^x} \mathbb{R}$$

$$\begin{matrix} \mathbb{R} \\ \mathbb{R} \end{matrix}$$

$h \mapsto e^x h$ is surjective $\forall x \in \mathbb{R}$
 (actually it is an isomorphism)

1'. $F : \mathbb{R} \rightarrow \mathbb{R}^+$

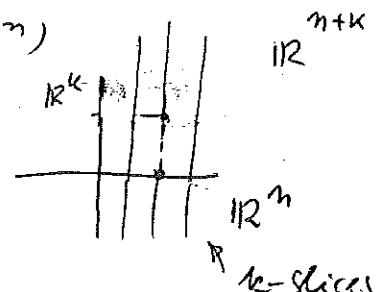
$$x \mapsto e^x$$

is a surjective submersion

2. $\pi : \mathbb{R}^{n+1} \rightarrow \mathbb{R}^n$

$$(x^1, \dots, x^n, x^{n+1}, \dots, x^{n+k}) \mapsto (x^1, \dots, x^n)$$

is a surjective submersion

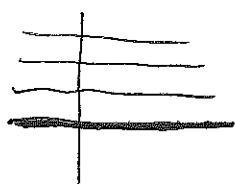


3. $i : \mathbb{R}^n \rightarrow \mathbb{R}^{n+k}$

$$(x^1, \dots, x^n) \mapsto (x^1, \dots, x^n, 0, 0, \dots, 0)$$

or (c_1, \dots, c_k)

embedding



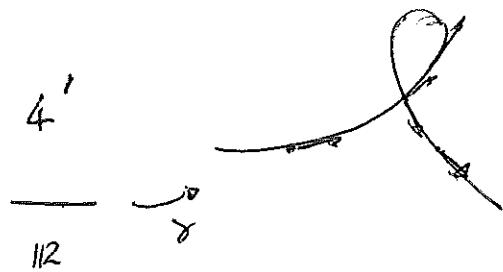
4. $\gamma: I \longrightarrow M$

open
interval

γ immersion: $\gamma'(t) \neq 0 \quad \forall t \in I$

γ embedding: γ injective, $\gamma'(t) \neq 0 \quad \forall t$, and

$\gamma: I \rightarrow \gamma(I)$ homeomorphism



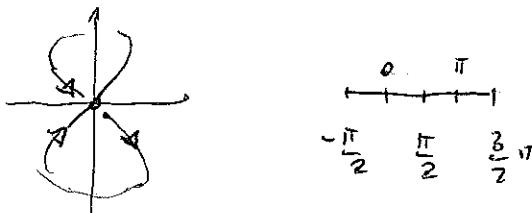
This is an immersion (we require $\gamma'(t) \neq 0 \quad \forall t \in I$)

but it is not an embedding

(γ is not injective, so it cannot be a homeomorphism)

4". $\gamma: (-\frac{\pi}{2}, \frac{3\pi}{2}) \longrightarrow \mathbb{R}^2$

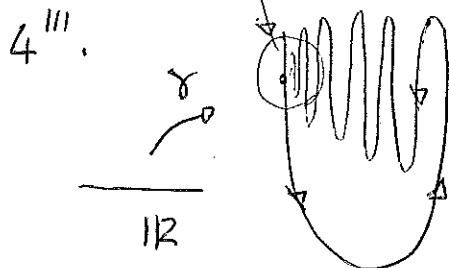
$$\gamma(t) = (\sin 2t, \cos t) \quad \alpha^2 = 4y^2(1-y^2)$$



I is not compact but $\gamma(I)$ is compact

($\Rightarrow \gamma$ cannot be a homeomorphism, since compactness is a topological property)

points like this one do not admit an arcwise connected neighbourhood



This is not an embedding:

\mathbb{R} is locally arcwise connected, but $\gamma(\mathbb{R})$ is not.

Again a

topological property

5. This is a very important example!

$$\gamma: \mathbb{R} \rightarrow \mathbb{T}^2 = S^1 \times S^1$$

$$t \mapsto \gamma(t) = (e^{2\pi i t}, e^{2\pi i ct})$$

$$c \in \mathbb{R} \setminus \mathbb{Q}$$

$\text{Im } \gamma$ is dense in $S^1 \times S^1 = \mathbb{T}^2$

$\mathbb{Z} \subset \mathbb{R}$ is a discrete set (i.e., without limit points), whilst $\gamma(\mathbb{Z}) \subset \mathbb{T}^2$ is not, whence

γ cannot be a homeomorphism onto $\gamma(\mathbb{R})$.

Also, one observes that $\text{Im}(\gamma)$ is not locally arcwise connected.

... According to Whitney's theorem, every f.d. manifold can be embedded in a suitable \mathbb{R}^N . However, this property is more effective in theoretical matters than in practice.

J. Nash extended Whitney's results to isometric embeddings of Riemannian manifolds in \mathbb{R}^N (so that the metric is inherited from \mathbb{R}^N), a major "tour-de-force"!

However, we close our discussion at this point.