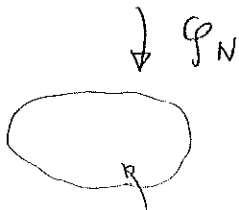
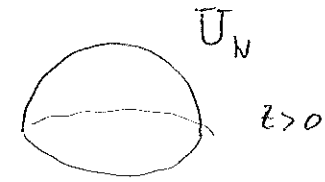


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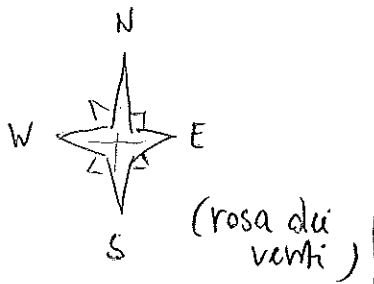
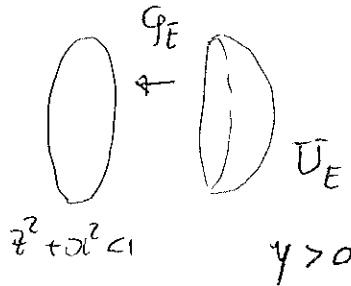
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equipped with the relative topology (inherited from the standard one in \mathbb{R}^3)



$$x^2 + y^2 < 1$$

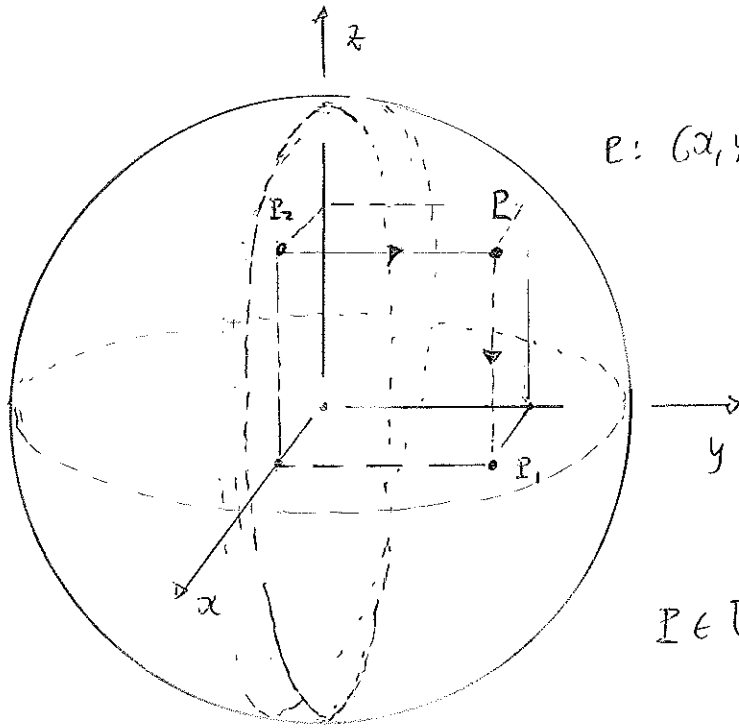


Compass-card

bussola

φ_E

φ_N



$P = (x, y, z)$

$P \in U_N \cap U_E$



$$y = \sqrt{1 - x^2 - z^2}$$

$$(z, x) \xrightarrow{\varphi_E^{-1}} (x, y, z)$$

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$$\varphi_E(U_E) = \{z^2 + x^2 < 1\}$$

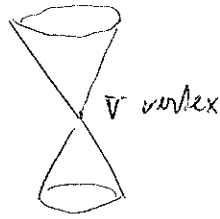
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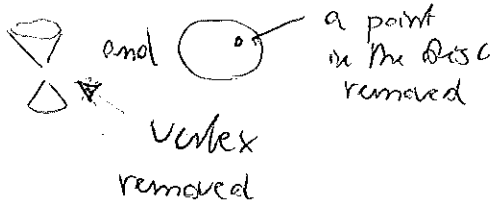


This is not a smooth manifold, and not even a topological manifold : ∇ does not possess a neighbourhood

homeomorphic to an open disc !



Why? Were it, then



would be homeomorphic, but this is false (the latter space is connected, the former is not)

2'



is a topological manifold (C^0)

$$x^2 + y^2 - z^2 = 0$$

$$z \geq 0$$

2''



∇ removed

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3. A remark on the concept of differentiable structure

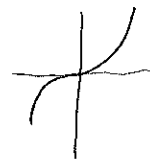
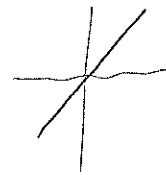
$$M_1 = (\mathbb{R}, t) \quad \varphi_1(t) = t$$

↑
atlas

consisting of a single chart

↓

$$M_2 = (\mathbb{R}, t^3) \quad \varphi_2(t) = t^3$$



* The two atlases are not compatible (upon requiring $k > 0$)
degree of differentiability

$$\varphi_2^{-1} \varphi_1 : t \xrightarrow{\varphi_1^{-1}} t \xrightarrow{\varphi_2} t^3 \quad \text{is smooth}$$

$$\varphi_1^{-1} \varphi_2 : t \xrightarrow{\varphi_2^{-1}} t^{\frac{1}{3}} \xrightarrow{\varphi_1} t^{\frac{1}{3}} \quad \text{is not smooth (nor } C^k \text{ } k \geq 1)$$



Therefore one has \mathbb{R} equipped with different differentiable structures (they are however equivalent

in a suitable sense. * The situation is really complicated in general:



Jungle of topological manifolds:

* For $\dim M \leq 3 \exists!$ differentiable structure (Munkres, Moise)

* In dimension > 3 , $\exists M$ which do not admit any differentiable structure.

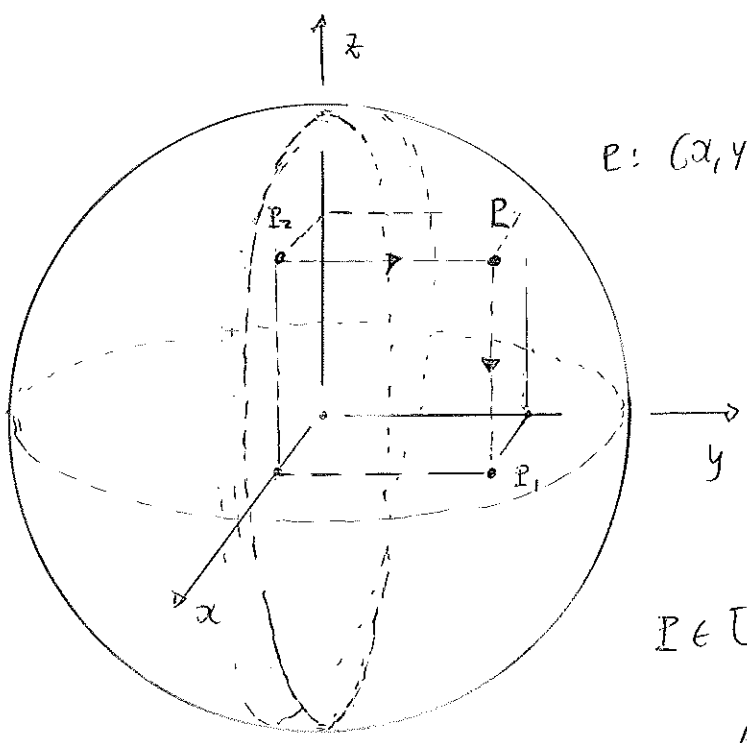
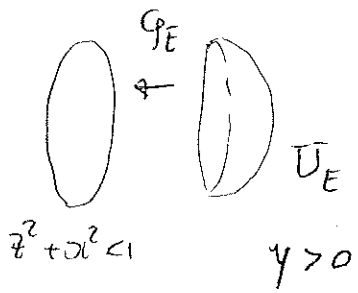
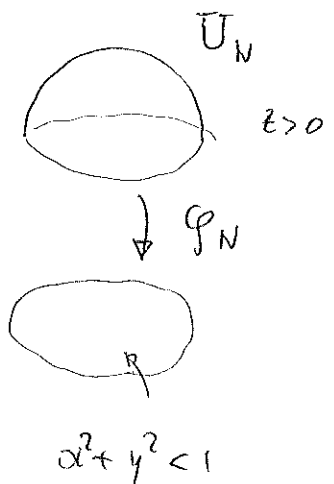
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We refrain from further delving into these fascinating topics.

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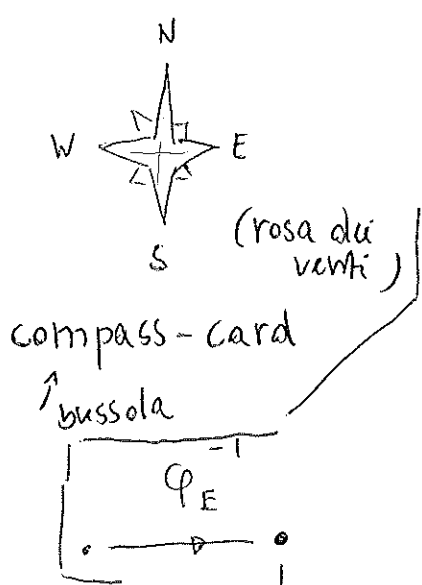


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$P \in U_N \cap U_E$



$y = \sqrt{1 - x^2 - z^2}$



compass: compasses a punte fisse: dividers

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$\varphi_E(U_E) = \{z^2 + x^2 < 1\}$

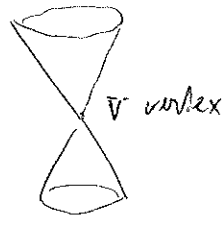
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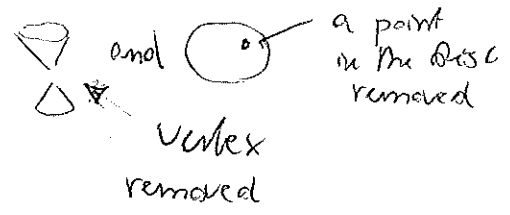


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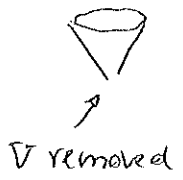


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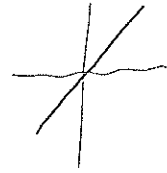


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$$M_1 = (\mathbb{R}, t)$$

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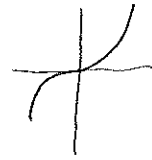
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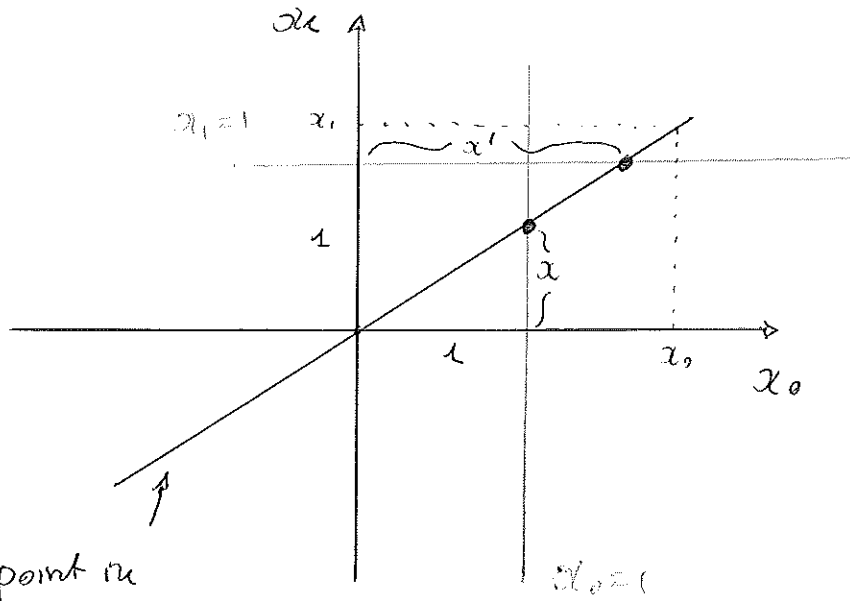
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a point in $\mathbb{R}P^1(\mathbb{R})$

inhomogeneous (affine) coordinate

$$\mathcal{U}_0 \ni \begin{matrix} \neq 0 \\ [x_0, x_1] \end{matrix} \xrightarrow{g_0} \begin{pmatrix} 1 \\ \frac{x_1}{x_0} \end{pmatrix} \equiv \alpha$$

removed

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in $\mathcal{U}_0 \cap \mathcal{U}_1$, $x_0 \neq 0, x_1 \neq 0$

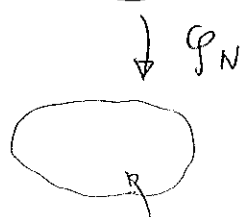
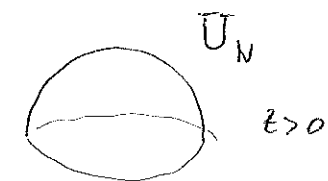
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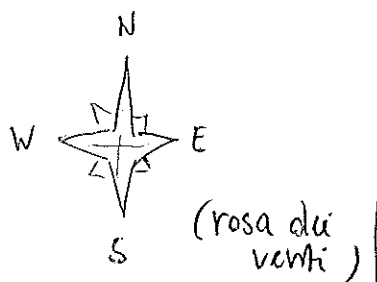
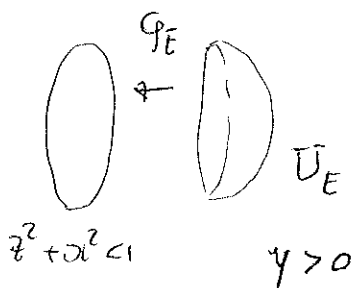
Smooth with smooth inverse

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compass-card

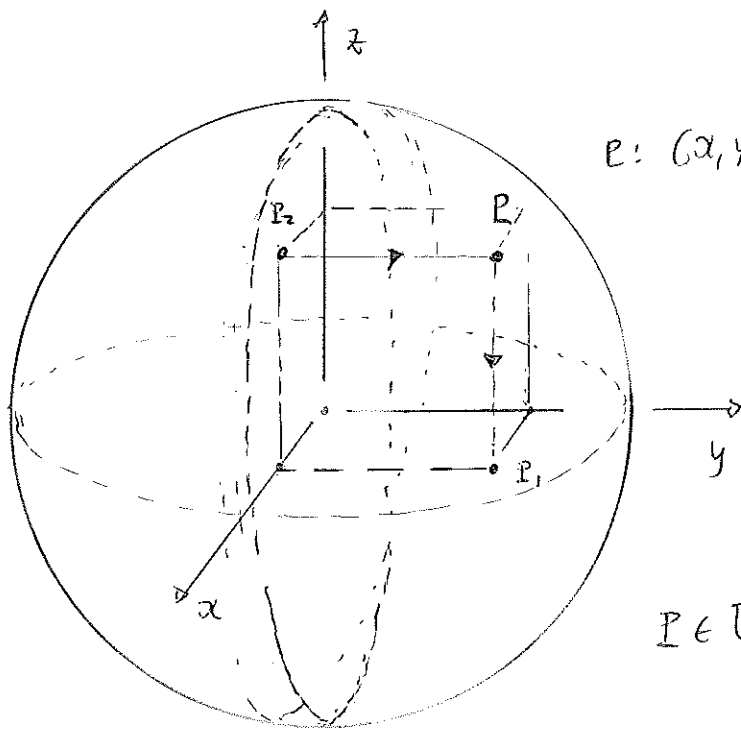
bussola

φ_E^{-1}

φ_E

φ_N

compass:
 compasses
 a punte fisse:
 dividers



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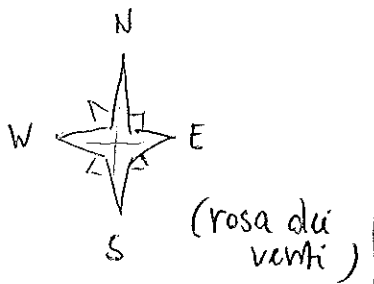
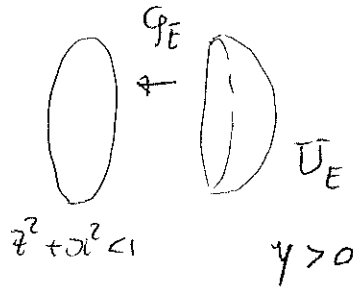
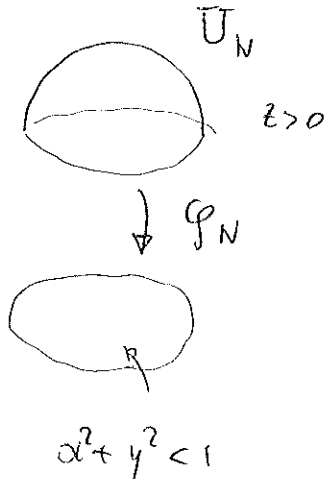
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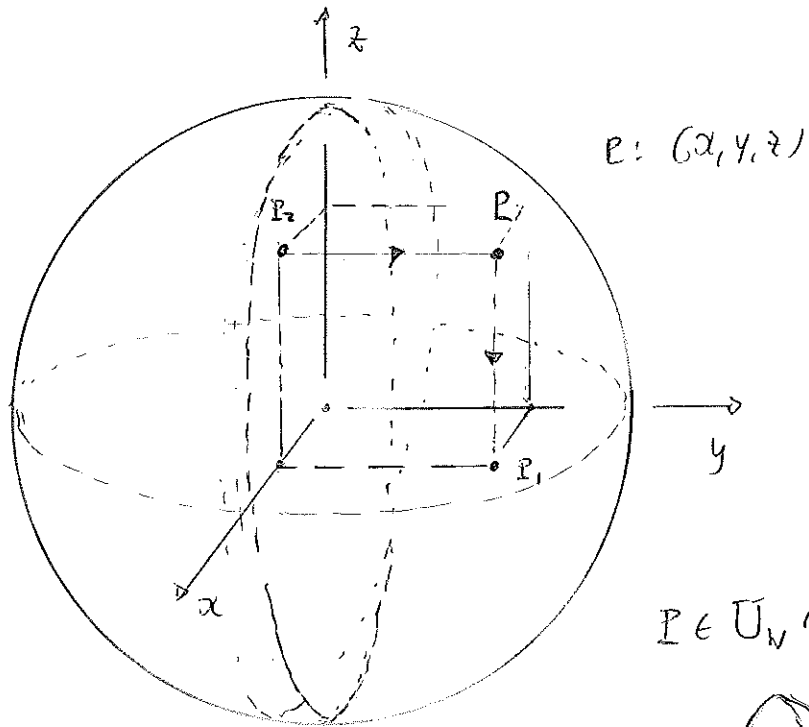
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compass-card
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compasses
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 a punte fisse:
 chiodi

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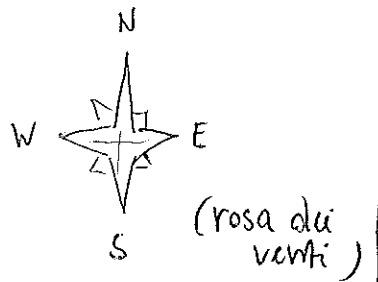
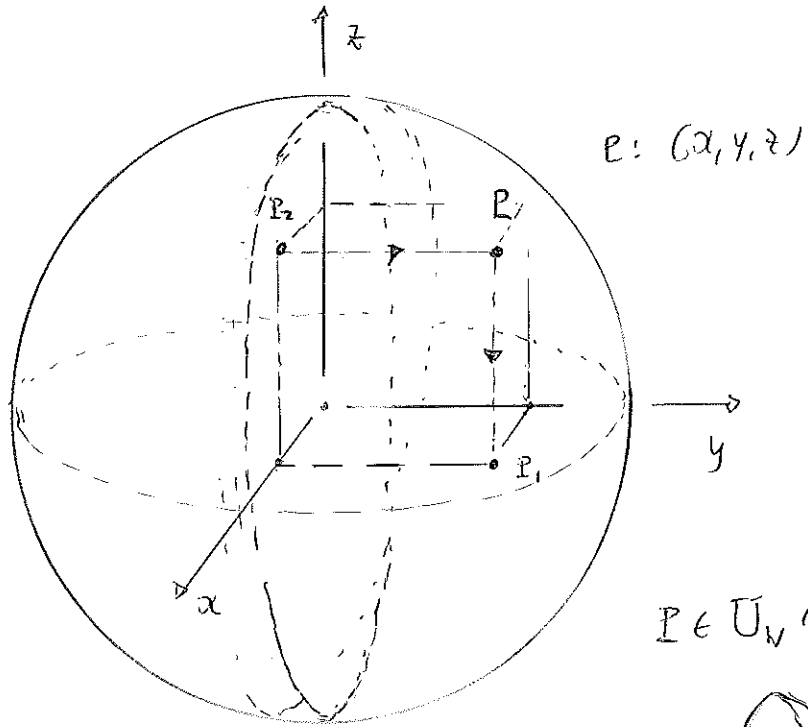
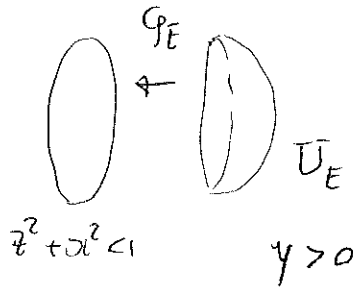
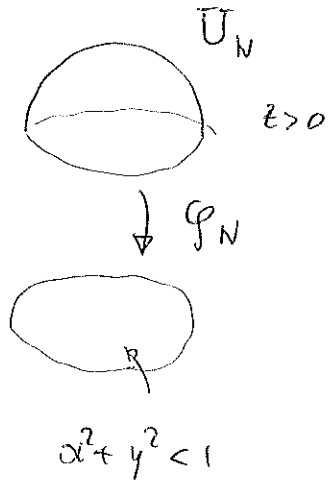
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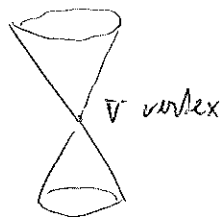
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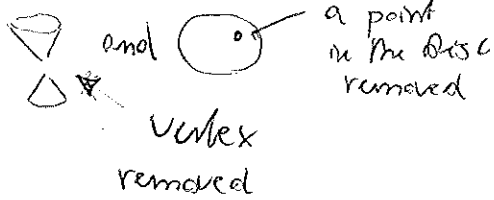
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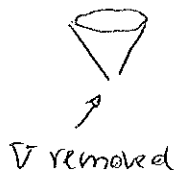


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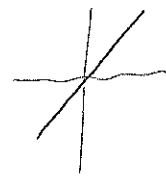
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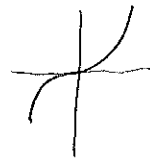
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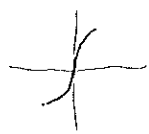
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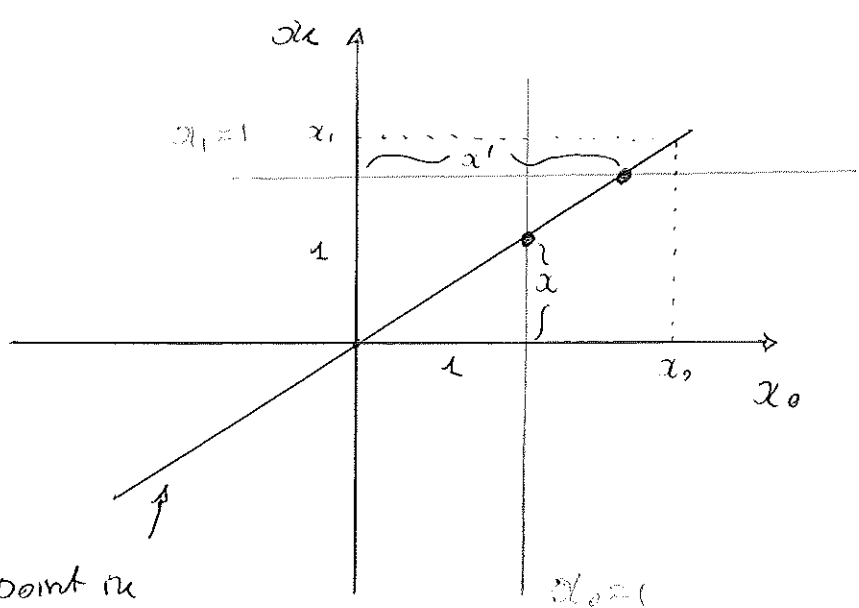
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in homogeneous (affine) coordinate

$$\mathcal{U}_0 \ni [x_0, x_1] \xrightarrow{g_0} \left(1, \frac{x_1}{x_0} \right) \equiv \alpha$$

$$\mathcal{U}_1 \ni [x_0, x_1] \xrightarrow{g_1} \left(\frac{x_0}{x_1}, 1 \right) \equiv \alpha'$$

removed

in $\mathcal{U}_0 \cap \mathcal{U}_1$, $x_0 \neq 0, x_1 \neq 0$

$$\alpha \xrightarrow{g_1 \circ g_0^{-1}} \alpha' = \frac{1}{\alpha}$$

$$\alpha' = \frac{1}{\alpha}$$

Smooth with smooth inverse

5. Projective spaces (real & complex)

$$\mathbb{P}^n(\mathbb{R}) \equiv \mathbb{P}(\mathbb{R}^{n+1})$$

$\mathbb{C} \qquad \qquad \mathbb{C}^{n+1}$

$$\varphi_i([x_0 \dots x_n]) = \left(\frac{x_0}{x_i}, \dots, \frac{x_i}{x_i}, \dots, \frac{x_n}{x_i} \right) \in \mathbb{R}^n$$

\mathbb{C}^n

homogeneous coordinates

1

↑

omitted

defined on

$$U_i = \{ [x] , x_i \neq 0 \}$$

let us calculate the transition maps, for $U_i \cap U_j \neq \emptyset$

(i.e. $x_i \neq 0, x_j \neq 0$)

$$\boxed{\varphi_j \circ \varphi_i^{-1}(x_1 \dots x_n) = \left(\frac{x_1}{x_j} \dots \frac{x_j}{x_j}, \frac{1}{x_j}, \dots, \frac{x_n}{x_j} \right)}$$

jth position

1

i-th-position

↓

1

x_j

x_j

x_j

= 1, omitted

In detail:

$$(x_1 \dots x_n) \xrightarrow{\varphi_i^{-1}} [x_1 \dots 1 \dots x_n] \in \mathbb{P}^n$$

insert at i-th pos.

↓

$$= \left(\begin{matrix} x_1 & \dots & x_i & \dots & x_n \\ x_i & & x_i & & x_i \end{matrix} \right)$$

|||

i-th-pos.

↓

$$\left(\frac{x_1}{x_i} \dots \frac{x_i}{x_i} \dots \frac{1}{x_i} \dots \frac{x_n}{x_i} \right)$$

1

(at jth position)

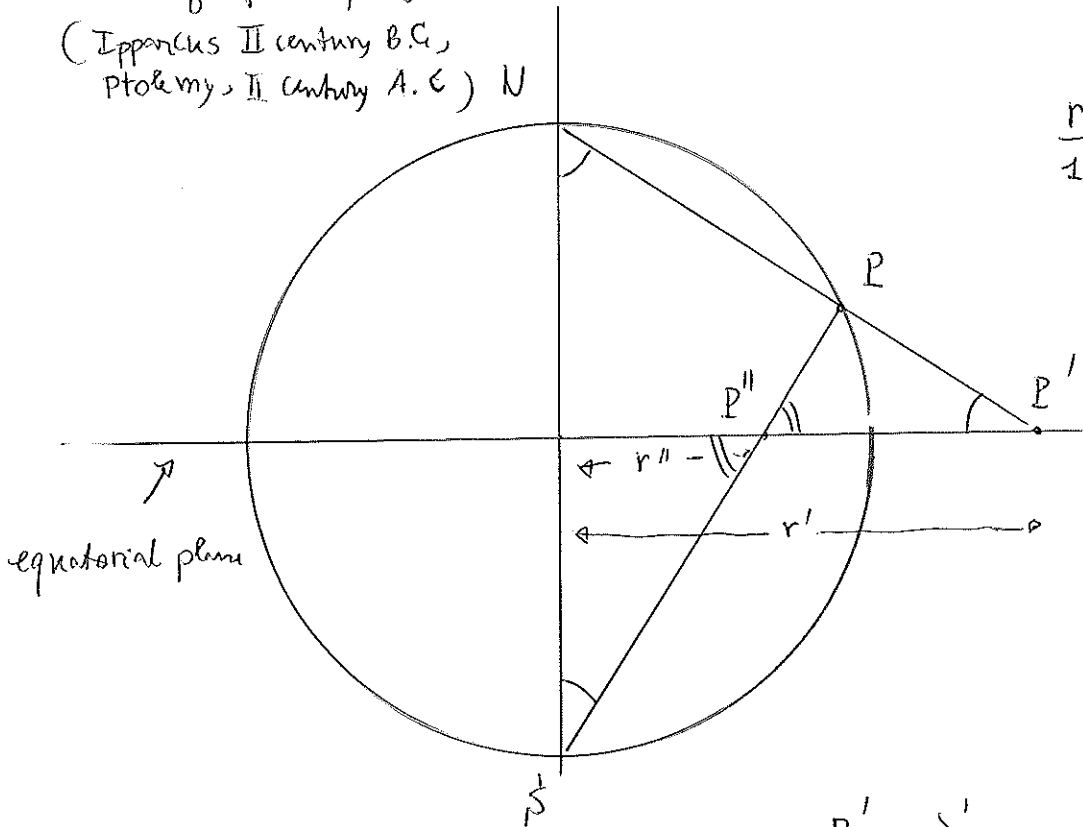
remove it

x_i: coordinates in \mathbb{R}^{n+1} (\mathbb{C}^{n+1})

These maps are smooth (and holomorphic in the complex case)

5'. The Riemann sphere (the complex projective line as a Riemann surface)

stereographic projections
(Epparchus II century B.C.,
Ptolemy, II century A.C.)



$$\frac{r'}{1} = \frac{1}{r''}$$

$$r' = \frac{1}{r''}$$

$$U_N = S^2 - \{N\}$$



$$U_S = S^2 - \{S\}$$



$$P' \leftrightarrow \zeta' \quad r' = |\zeta'|$$

$$P'' \leftrightarrow \zeta'' \quad r'' = |\zeta''|$$

$$S^2 = U_N \cup U_S$$

$$\varphi_N: P \mapsto P'$$

$$\varphi_S: P \mapsto P''$$

If $P \notin \{N, S\}$ they are both defined

$$\varphi_N \circ \varphi_S^{-1}: \begin{array}{ccc} P'' & \xrightarrow{\varphi_S^{-1}} & P & \xrightarrow{\varphi_N} & P' \\ \mathbb{C} & & & & \mathbb{C} \\ \text{equatorial plane } \zeta'' & \xrightarrow{\quad} & & & \zeta' \end{array}$$

real form

$$x' + iy' = \frac{1}{x'' + iy''} =$$

$$= \frac{x'' - iy''}{x''^2 + y''^2} \Rightarrow$$

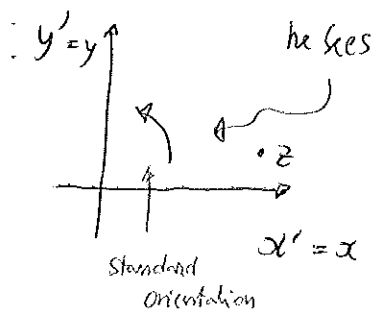
$$\begin{cases} x' = \frac{x''}{x''^2 + y''^2} \\ y' = \frac{-y''}{x''^2 + y''^2} \end{cases}$$

$$\zeta' = \frac{1}{\zeta''}$$

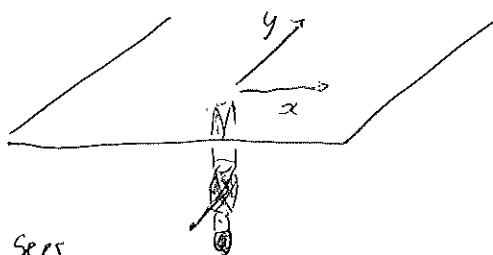
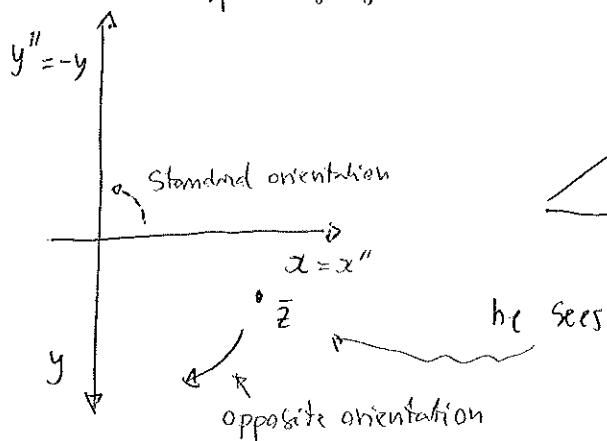
for suitable orientations (see further on)

Remark on orientation

take two copies of the equatorial plane $\cong \mathbb{C}$



⚡ conjugation is involved

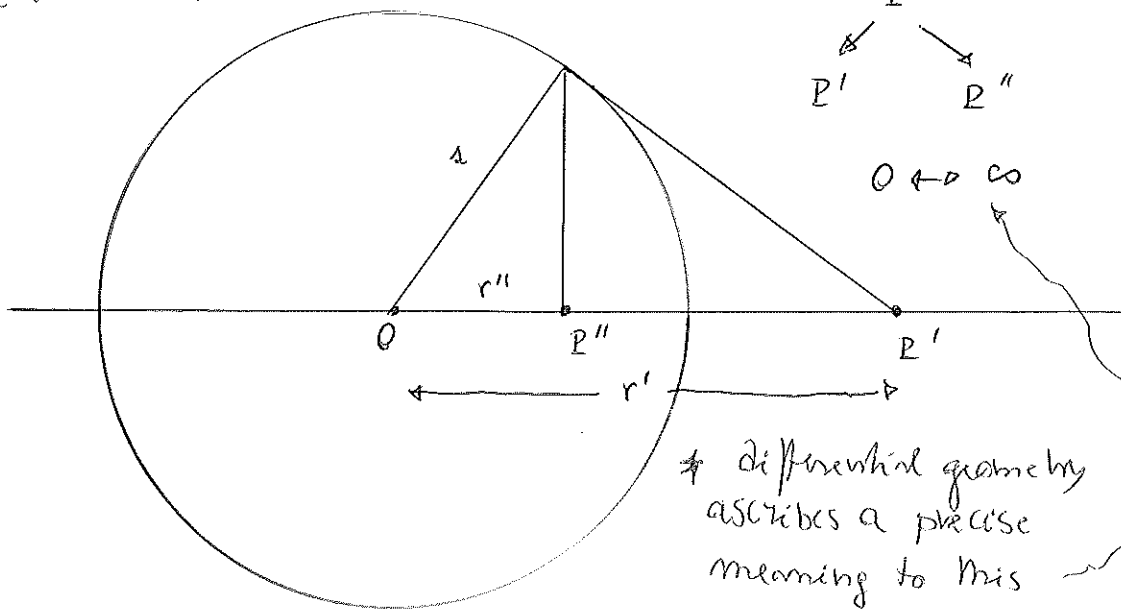


notice this

$$\underbrace{x'' + iy''}_{z''} = \frac{1}{\underbrace{x' + iy'}_{z'}} = \frac{x' - iy'}{x'^2 + y'^2}$$

From remark: P' and P'' are related by a circular inversion

$$r' \cdot r'' = 1$$

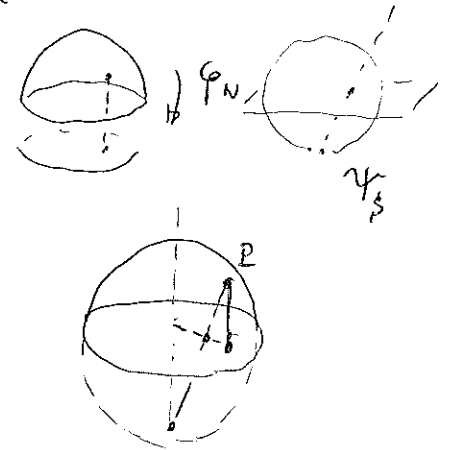
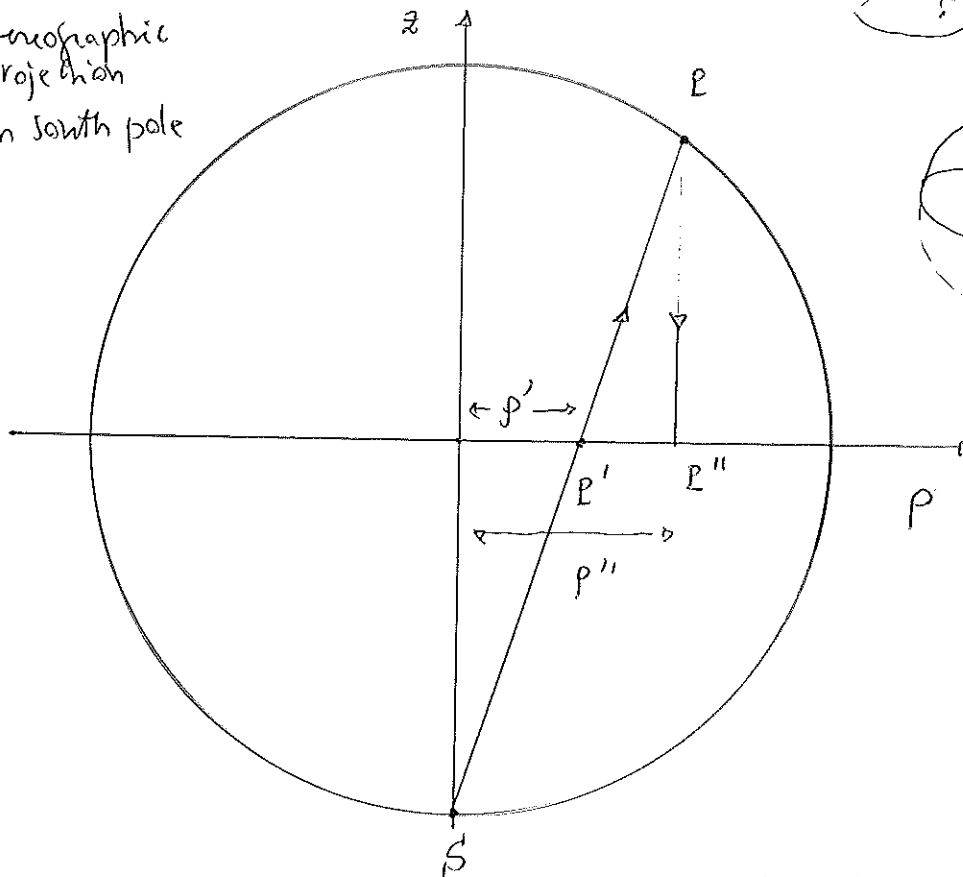


⚡ differential geometry ascribes a precise meaning to this

6. Notice that we exhibited two atlases for the sphere. Let us check that they are compatible; it is then enough to show that the two charts below are compatible

$\varphi_N: U_N \rightarrow \mathbb{R}^2$ considered previously

ψ_S : stereographic projection from south pole



This is geometrically clear. Find the relationship between p' and p''

They define the same differentiable structure