

Lectures on

DIFFERENTIAL GEOMETRY AND TOPOLOGY

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Lecture XII

* Smooth maps between manifolds

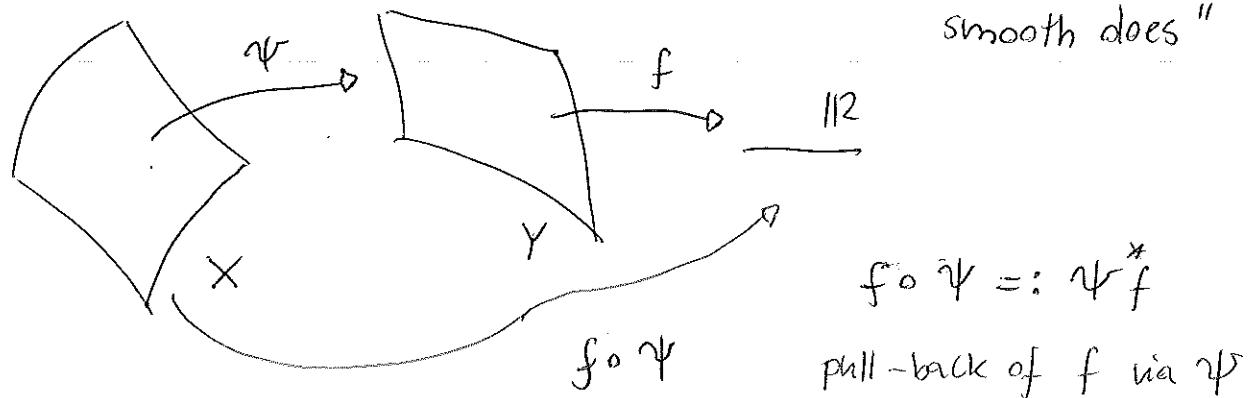
Let X, Y be differentiable manifolds of dimension n and m respectively

* A map $\psi: X \rightarrow Y$ is said to be smooth

if, whenever $f \in C^\infty(Y, \mathbb{R})$, then $f \circ \psi \in C^\infty(X, \mathbb{R})$

smooth function
on Y

"smooth is who
smooth does"



"knowing functions on X one knows X "

Def. $\psi: X \rightarrow Y$ is said to be a (smooth) diffeomorphism

- If
- ψ is bijective (and smooth)
 - ψ^{-1} is smooth

Locally, $\psi: X \rightarrow Y$ induces smooth maps from \mathbb{R}^n to \mathbb{R}^m
(upon applying the definition to local coordinate functions)

• Smooth maps between
manifolds p. 1

• Differential p. 2

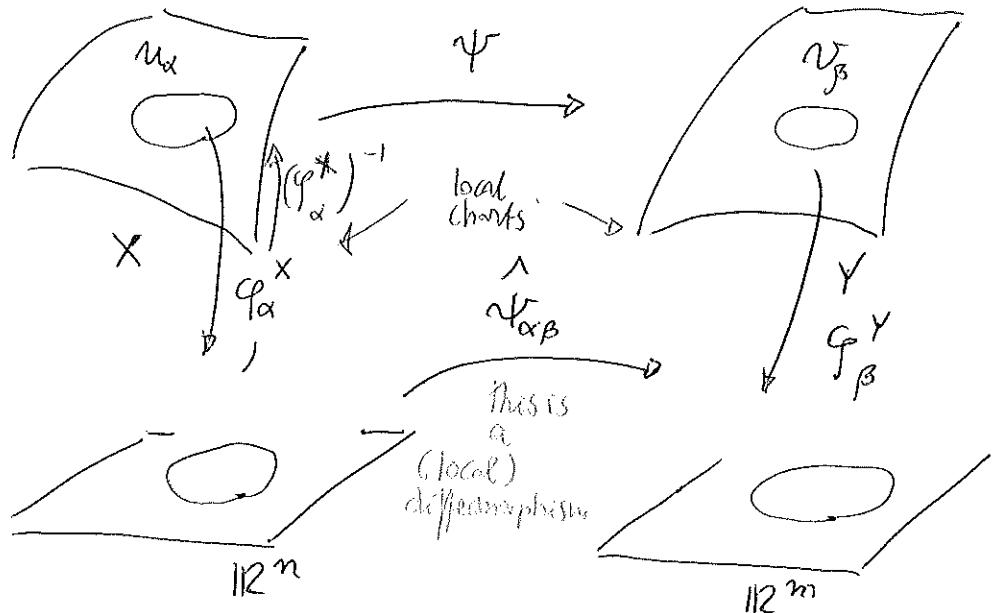
• Example p. 6

• Tangent & cotangent p. 8
bundles

• Tensor bundles p. 12

• Riemannian p. 13
metrics

• Behaviour under smooth p. 14
maps



if ψ

$$\psi_{\alpha\beta}^1 = g_{\beta}^Y \circ \psi \circ (g_{\alpha}^X)^{-1}$$

is smooth,
and $f \in C^{\infty}(Y, \mathbb{R})$,
then $f \circ \psi = \psi^* f$

$\in C^{\infty}(X, \mathbb{R})$
by definition

* Differentiable of a smooth map.

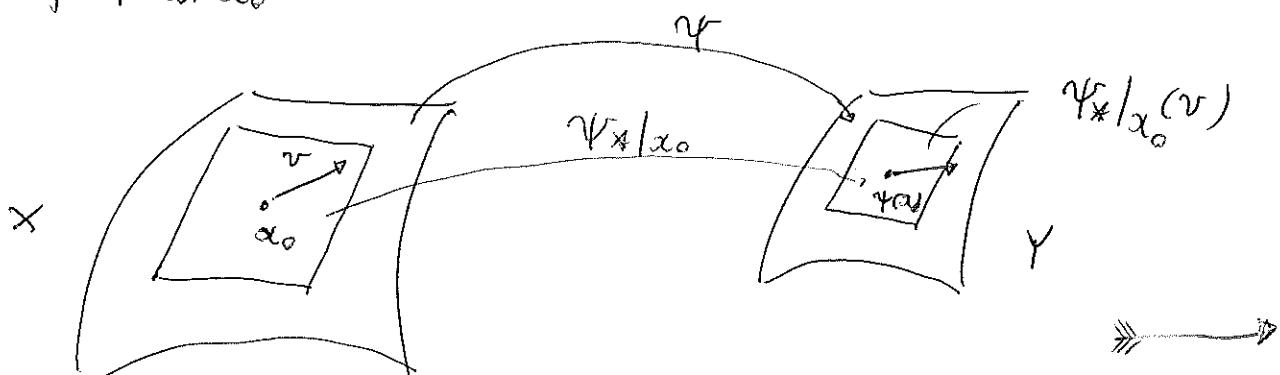
Let $\psi: X \rightarrow Y$ smooth

and $x_0 \in X$. One can define

$$d\psi|_{x_0} = \psi_*|_{x_0}: T_{x_0} X \longrightarrow T_{\psi(x_0)} Y$$

differential
(push-forward)
of ψ at x_0

$$v \longmapsto \psi_*|_{x_0}(v)$$

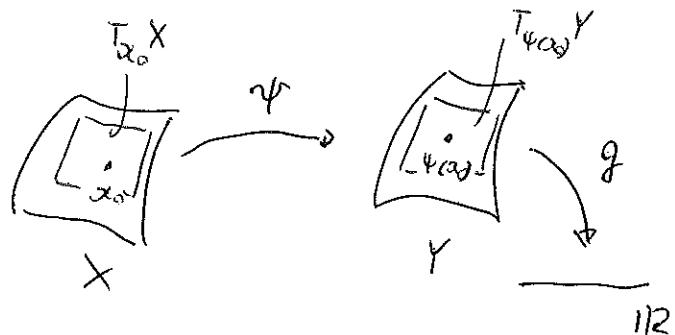


via the position

$$(\psi_*|_{x_0}(v))(g) := v(g \circ \psi)$$

\cap \cap \cap
 $T_{x_0} X$ $C^0(Y, \psi(x_0), \mathbb{R})$ $C^0(X, x_0, \mathbb{R})$

This is a derivation,
acting on functions
defined on a neighbourhood
of $\psi(x_0)$



One finds that

$$(\psi_*|_{x_0}(v))(g) = \sum_{j=1}^m \left[v(y^j \circ \psi) \frac{\partial}{\partial y^j} \right] (g)$$

In particular

$$\psi_*|_{x_0} \left(\frac{\partial}{\partial x^i} \right) = \sum_{j=1}^m \frac{\partial}{\partial x^i} (y^j \circ \psi) \frac{\partial}{\partial y^j}$$

$$\frac{\partial}{\partial x^i} \mapsto \frac{\partial y^j}{\partial x^i} \frac{\partial}{\partial y^j}$$

$$\frac{\partial}{\partial x} \mapsto J^T \frac{\partial}{\partial y}$$

$$\Psi: X \rightarrow Y$$

Let us provide some details

φ : coordinate system $(x^1 \dots x^n)$ around $x_0 \in X$
 local chart

$$x : \quad = \quad (y^1 \dots y^m) \text{ around } y_0 \in Y$$

Complete:

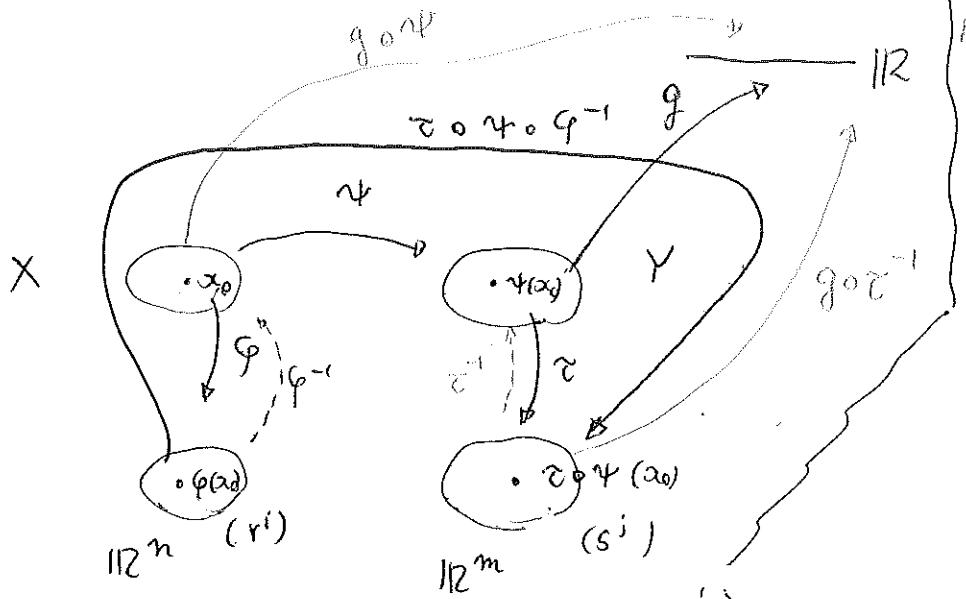
$$(\psi_*|_{x_0}(v))(g) = v(g \circ \psi) = \sum_{i=1}^n a^i \frac{\partial}{\partial x^i}(g \circ \psi)$$

$$= \sum_{i=1}^n a^i \frac{\partial}{\partial r^i} (\underbrace{g \circ \varphi^{-1} \circ \varphi}_{\text{underbrace}} \circ \underbrace{\psi \circ g^{-1}}_{\text{underbrace}}) |_{g(\alpha_0)}$$

Chain rule

$$= \sum_{i=1}^n a^i \sum_{j=1}^m \left. \frac{\partial}{\partial s_j} (g \circ \tau^{-1}) \right|_{\tau \circ \Psi(x_0)} \cdot \left. \frac{\partial}{\partial r_i} (s_j \circ \tau \circ \Psi \circ \varphi^{-1}) \right|_{g(x_0)}$$

$$\text{Coordinate maps on } M^m = \sum_{i=1}^n \sum_{j=1}^m a^i \frac{\partial g}{\partial y^j} \cdot \frac{\partial}{\partial x^i} (y_j \circ \psi)$$



$$= \left[\sum_{j=1}^m w(y_j \circ \psi) \frac{\partial}{\partial y_j} \right] (g)$$

This is indeed a tangent vector at $\alpha(0)$.)

The diagram illustrates coordinate transformations between local and global frames. It features two main regions separated by a diagonal line.

- Left Region (Local Coordinates):** A point q is shown in a local coordinate system. A curve labeled r^j connects it to a point r^j in a global coordinate system. The equation $\alpha^j = r^j \circ q$ is written below.
- Right Region (Global Coordinates):** A point s^j is shown in a global coordinate system. A curve labeled τ connects it to a point y^j in a local coordinate system. The equation $y^j = s^j \circ \tau$ is written below.
- Diagonal Line:** A diagonal line separates the two regions. The word "similarly" is written above the line, indicating the relationship between the two coordinate transformations.
- Bottom Right:** The text "XII - 4" is located at the bottom right of the diagram area.

We find, in particular

$$\psi_*|_{\alpha_0} : T_{\alpha_0} X \longrightarrow T_{\psi(\alpha_0)} Y$$

$$\frac{\partial}{\partial x^i}|_{\alpha_0} \longmapsto \sum_{j=1}^m \underbrace{\frac{\partial}{\partial x^j} (y_j \circ \psi) \frac{\partial}{\partial y^j}}_{(\psi_*|_{\alpha_0})_{ji}} \sim J^T$$

Let us also check that if $X \xrightarrow{\psi} Y \xrightarrow{\Phi} Z$

$$\text{then } d(\Phi \circ \psi) = d\Phi \circ d\psi \quad \begin{matrix} \text{generalized chain} \\ \text{rule} \end{matrix}$$

\nwarrow as homeomorphisms

\nearrow matrix product.

associativity of \circ

$$[(\Phi \circ \psi)_*(v)](h) \underset{\text{def}}{=} v(h \circ (\Phi \circ \psi)) = v((h \circ \Phi) \circ \psi)$$

$$= \psi_*(v)(h \circ \Phi) = \Phi_*(\psi_*(v))(h)$$

$$= [(\Phi_* \circ \psi_*)(v)](h) \quad \square$$

* Example. Let $M = \mathbb{R}^2 \setminus \{(x, 0) | x \geq 0\}$

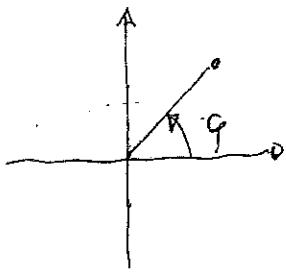
$$\Psi: (\rho, \varphi) \xrightarrow{\psi: \mathbb{R}^2} (x, y) \quad \begin{cases} x = \rho \cos \varphi \\ y = \rho \sin \varphi \end{cases}$$

$\rho > 0$
 $\varphi \in (0, 2\pi)$

—

$\Psi_* : \begin{cases} dx = d\rho \cos \varphi - \rho \sin \varphi d\varphi \\ dy = d\rho \sin \varphi + \rho \cos \varphi d\varphi \end{cases}$

III
 Ψ_*



$$\begin{pmatrix} \cos \varphi & -\rho \sin \varphi \\ \sin \varphi & \rho \cos \varphi \end{pmatrix}$$

$$\frac{\partial}{\partial \rho} \mapsto \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

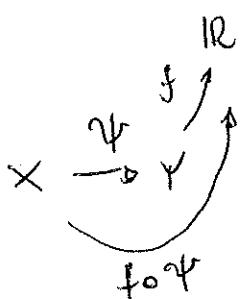
$$\frac{\partial}{\partial \varphi} \mapsto \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\Psi_* \left(\frac{\partial}{\partial \rho} \right) = \cos \varphi \frac{\partial}{\partial x} + \sin \varphi \frac{\partial}{\partial y} = \frac{x}{\sqrt{x^2+y^2}} \frac{\partial}{\partial x} + \frac{y}{\sqrt{x^2+y^2}} \frac{\partial}{\partial y}$$

$$\Psi_* \left(\frac{\partial}{\partial \varphi} \right) = -\rho \sin \varphi \frac{\partial}{\partial x} + \rho \cos \varphi \frac{\partial}{\partial y} = -y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y}$$

This is of course in agreement with the general definition

$$(\Psi_* X)(f) = X(f \circ \Psi)$$



Take $X = \frac{\partial}{\partial \rho}$. Compute:

$$\Psi_* \left(\frac{\partial}{\partial \rho} \right) (f) = \frac{\partial}{\partial \rho} (f \circ \Psi) = \frac{\partial f}{\partial x} \frac{\partial x}{\partial \rho} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial \rho}$$

" $f = f(x, y)$ "

" $f = f(\rho, \varphi)$ "

$$= \frac{\partial f}{\partial x} \frac{\cos \varphi}{\sqrt{x^2+y^2}} + \frac{\partial f}{\partial y} \frac{\sin \varphi}{\sqrt{x^2+y^2}} \Rightarrow \boxed{\Psi_* \left(\frac{\partial}{\partial \rho} \right) = \frac{x}{\sqrt{x^2+y^2}} \frac{\partial}{\partial x} + \frac{y}{\sqrt{x^2+y^2}} \frac{\partial}{\partial y}} \quad | \checkmark$$

"remove f"

Similarly:

$$\Psi_* \left(\frac{\partial}{\partial \varphi} \right) (f) = \frac{\partial}{\partial \varphi} (f \circ \Psi) = \frac{\partial f}{\partial x} \frac{\partial x}{\partial \varphi} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial \varphi}$$

$$= \frac{\partial f}{\partial x} (-\rho \sin \varphi) + \frac{\partial f}{\partial y} (\rho \cos \varphi) \Rightarrow \boxed{\begin{aligned} \Psi_* \left(\frac{\partial}{\partial \varphi} \right) &= \\ -y \frac{\partial}{\partial x} + \alpha \frac{\partial}{\partial y} \end{aligned}}$$

Let us examine this "classical" computation as well (useful in general)

$$\begin{aligned} \frac{\partial f}{\partial p} &= \frac{\partial f}{\partial x} \frac{\partial x}{\partial p} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial p} & \begin{pmatrix} \frac{\partial x}{\partial p} & \frac{\partial y}{\partial p} \\ \frac{\partial x}{\partial q} & \frac{\partial y}{\partial q} \end{pmatrix} &= J^t \\ \frac{\partial f}{\partial q} &= \frac{\partial f}{\partial x} \frac{\partial x}{\partial q} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial q} \end{aligned}$$



that is:
(remove f)

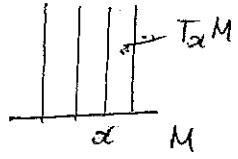
$$\begin{pmatrix} \frac{\partial}{\partial p} \\ \frac{\partial}{\partial q} \end{pmatrix} = \begin{pmatrix} \cos \varphi & \sin \varphi \\ -\rho \sin \varphi & \rho \cos \varphi \end{pmatrix} \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \end{pmatrix}$$

$$\left\{ \begin{array}{l} \frac{\partial}{\partial p} = \cos \varphi \frac{\partial}{\partial x} + \sin \varphi \frac{\partial}{\partial y} \\ \frac{\partial}{\partial q} = -\rho \sin \varphi \frac{\partial}{\partial x} + \rho \cos \varphi \frac{\partial}{\partial y} \end{array} \right.$$

$\frac{\partial}{\partial p}$ and $\frac{\partial}{\partial q}$ are viewed,
concretely,
as linear combinations
of $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$ but

* The tangent bundle TM

Let M be a (smooth) manifold
disjoint union



$$\text{Let } TM = \bigsqcup_{x \in M} T_x M$$

\uparrow tangent bundle of M

\uparrow tangent space at x

$$\begin{aligned} \text{Cotangent bundle of } M & T^*M = \bigsqcup_{x \in M} T_x^*M \\ & \approx (T_x M)^* \text{ dual of } T_x M \\ & \equiv \text{cotangent space at } x \end{aligned}$$

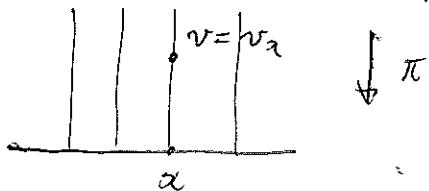
* TM and T^*M are naturally endowed with a manifold structure. Let us focus on TM (T^*M is treated similarly)

Let $A = \{(u_\alpha, g_\alpha)\}_{\alpha \in \Omega}^y$ be an atlas for M

\uparrow
some index set

Let $\pi: TM \rightarrow M$ be the natural projection map.

$$v \equiv v_\alpha - \mapsto \alpha$$

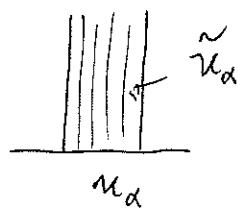


any $v \in TM$ belongs

to one and only one $T_\alpha M$
for $\alpha \in M$

$$\text{Let } \tilde{u}_\alpha = \pi^{-1}(u_\alpha) \approx u_\alpha \times \mathbb{R}^n$$

they give rise to



\uparrow
Set

$$\tilde{g}_\alpha: (\alpha, \sum_{i=1}^n b^i \frac{\partial}{\partial x^i}) \mapsto (x^i, b^i)$$

$$\begin{array}{ccc} \cap & & \parallel \\ T_\alpha M & \xrightarrow{\quad \quad \quad} & \text{No } g \\ & & \text{local coordinates} \end{array}$$

$\tilde{A} = \{(\tilde{u}_\alpha, \tilde{g}_\alpha)\}_{\alpha \in \Omega}$ becomes an atlas
for TM

* TM can be topologized according to the second definition; it is clear
that it has a countable basis and is Hausdorff if M is such.

The transition functions are readily obtained via the following computation (abbreviated notation, together with Einstein's convention)

$$b^i \frac{\partial f}{\partial x^i} = b^i \frac{\partial f}{\partial y^j} \frac{\partial y^j}{\partial x^i}$$

incident argument

coordinate change
 $y = g(x)$

$$= \left(b^i \frac{\partial y^j}{\partial x^i} \right) \frac{\partial f}{\partial y^j} \quad (b^i) \mapsto (b'^i)$$

$\underbrace{(b'^j)}$

$$b'^i = b'^k \frac{\partial y^i}{\partial x^k} = \frac{\partial y^i}{\partial x^k} b^k$$

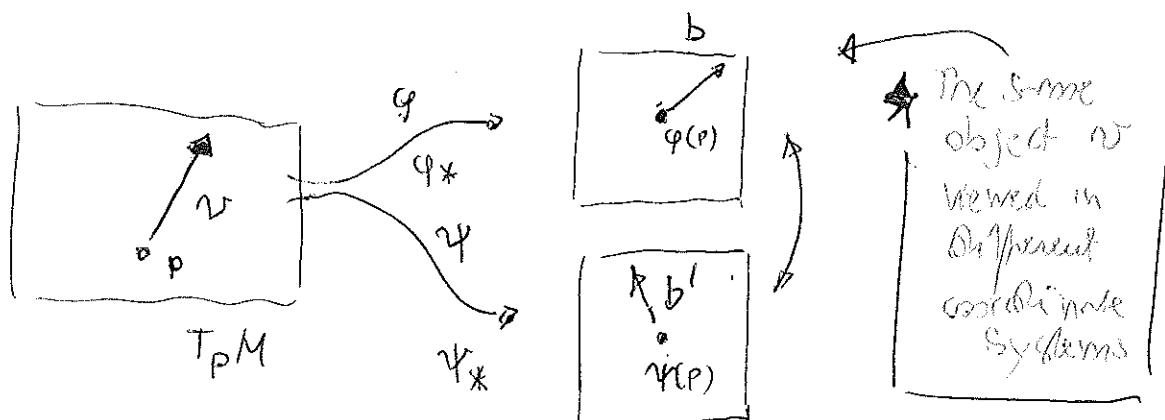
$$\begin{array}{c} \boxed{} \\ b' \end{array} = \boxed{g_*} \begin{array}{c} \boxed{} \\ b \end{array}$$

\uparrow
just a relabeling

This is fully consistent with the interpretation of the b 's as velocity vectors of curves

transition maps:

$$(x, b) \mapsto (y, b')$$

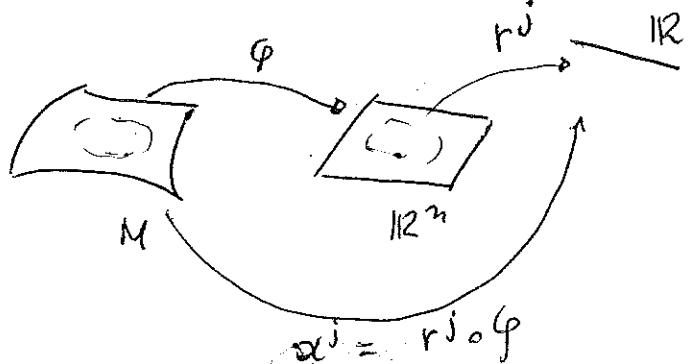


* The cotangent bundle

A similar treatment can be devised for the cotangent bundle T^*M . Charts (α given an atlas for M):

$$\tilde{\varphi}_\alpha : (\alpha, \sum_{i=1}^m b_i dx^i) \mapsto (x^i, b^i)$$

\uparrow \nwarrow
 $T_x^* M$ notice:
 dx^i is the differential
of the j -th coordinate function x^j



in accordance with
the general definition

$$\eta_f : X \rightarrow Y$$

$$\eta_{f*}^\alpha : T_x X \rightarrow T_{f(x)} Y$$

Remark: Cotangent spaces are fundamental in mechanics, being examples of phase spaces (symplectic manifolds), i.e. receptacles of positions and momenta of point particles.

Duals of velocities

remember
that identification
with dual space
is not canonical



Again work out the transition functions

$$b_i dx^i = \underbrace{b'_i}_{\frac{\partial x^i}{\partial y^j}} dy^j$$

$$b \mapsto b'$$

$$(b_i) \mapsto (b_{ik} \frac{\partial x^k}{\partial y^i}) = (\frac{\partial x^k}{\partial y^i} b_{ik}) \in (b'_i)$$

↑
relabelling

* again notice the different behaviours

(contravariance vs covariance)

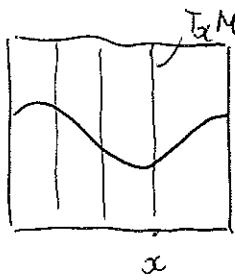
transition maps

$$(a, b) \mapsto (y, b')$$

↑
covector
— — — — —

* vector fields (notation: $\mathcal{X}(M)$) are the smooth sections on M of TM , i.e. given $\pi: TM \rightarrow M$

(canonical projection: it is a smooth map), $X: M \rightarrow TM$ (smooth) such that $\pi \circ X = id_M$, i.e. $X(x) \in T_x M$



$$\leftarrow x \in \mathcal{X}(M) \quad \forall x \in M$$

* differential k-forms (notation: $\Lambda^k(M)$)
 \cong smooth sections of T^*M ; $\omega: M \rightarrow T^*M$
 with $\pi \circ \omega = id_M$ ($\pi: T^*M \rightarrow M$ canonical projection)

* Tensor bundles

One can similarly define tensor bundles, whose sections are tensor fields

$$T^{(p,q)}(M) \ni (\alpha, t^I_J \frac{\partial}{\partial x^I} \otimes dx^J)$$

$T_x^* M \otimes \dots \otimes T_x^* N \otimes T_x M \otimes \dots \otimes T_x M$

↓ local chart

notation: $\gamma^{(p,q)}(M)$ (α, t^I_J)
R components

* transition maps: $y = y(x)$

$$t^{i_1 \dots i_p}_{j_1 \dots j_q} \frac{\partial}{\partial x^{i_1}} \otimes \frac{\partial}{\partial x^{i_p}} dx^{j_1} \otimes \dots \otimes dx^{j_q}$$

insert f fictitious Einstein

$$\frac{\partial f}{\partial x^{i_1}} = \frac{\partial f}{\partial y^{e_1}} \frac{\partial y^{e_1}}{\partial x^{i_1}}$$

etc...

$$dx^{i_1} = \frac{\partial x^{i_1}}{\partial y^{e_1}} dy^{e_1} + \text{other terms}$$

$$t^{i_1 \dots i_p}_{j_1 \dots j_q} \frac{\partial y^{e_1}}{\partial x^{i_1}} \cdot \frac{\partial y^{e_p}}{\partial x^{i_p}} \frac{\partial x^{j_1}}{\partial y^{e_1}} \dots \frac{\partial x^{j_q}}{\partial y^{e_q}} \frac{\partial}{\partial y^{e_1}} \otimes \dots \otimes \frac{\partial}{\partial y^{e_p}} dy^{e_1} \otimes \dots \otimes dy^{e_p}$$

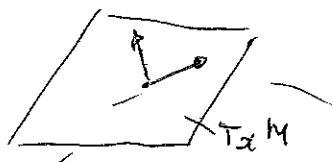
$$t'_{l_1 \dots l_q}^{e_1 \dots e_p}$$

Concisely: $t^I_J \frac{\partial}{\partial x^I} \otimes dx^J = t^I_J \frac{\partial y^L}{\partial x^I} \frac{\partial x^J}{\partial y^H} \frac{\partial}{\partial y^L} \otimes dy^H$

$$t'_{H}^L = t^I_J \frac{\partial y^L}{\partial x^I} \frac{\partial x^J}{\partial y^H}$$

↙ sum over I and J

* Example : A Riemannian metric on M is a smoothly varying family of inner products on $T_x M$, $x \in M$; it is a symmetric, positive definite (at each point) element of $\mathcal{S}^{(0,2)}(M)$



inner product
defined here

of $\mathcal{S}^{(0,2)}(M)$

locally:

$$x \mapsto g_{ij} dx^i dx^j$$

$$dx^i dx^j$$

$$= \frac{1}{2} (dx^i \otimes dx^j)$$

$$+ \frac{1}{2} (dx^j \otimes dx^i)$$

\Leftrightarrow symmetric tensor product

Let us check its transformation law:

$$\begin{aligned} g_{ij} dx^i dx^j &= g_{ij} \frac{\partial x^i}{\partial y^k} dy^k \frac{\partial x^j}{\partial y^l} dy^l \\ &\quad \text{as a function of } x \\ &= g_{ij} \frac{\partial x^i}{\partial y^k} \frac{\partial x^j}{\partial y^l} dy^k dy^l \\ &\quad \text{as a function of } y \\ &= g'_{kl} dy^k dy^l \end{aligned}$$

$$dy^k dy^l =$$

$$\frac{1}{2} (dx \otimes dy - dy \otimes dx)$$

+ antisymmetric tensor product

$$\begin{cases} dy^k dy^l = \\ dy dy + dx dy \end{cases}$$

$$g'_{kl} = g_{ij} \frac{\partial x^i}{\partial y^k} \frac{\partial x^j}{\partial y^l}$$

(This is a function of y)

Once one gets used to this kind of computations
they are easily performed automatically.

* Behaviour of vector fields and differential forms under smooth maps

* $\mathcal{X}(M)$ | Notice that in general, the push-forward
 $\psi_* : T\psi : TM \rightarrow TN$ of $\psi : M \rightarrow N$

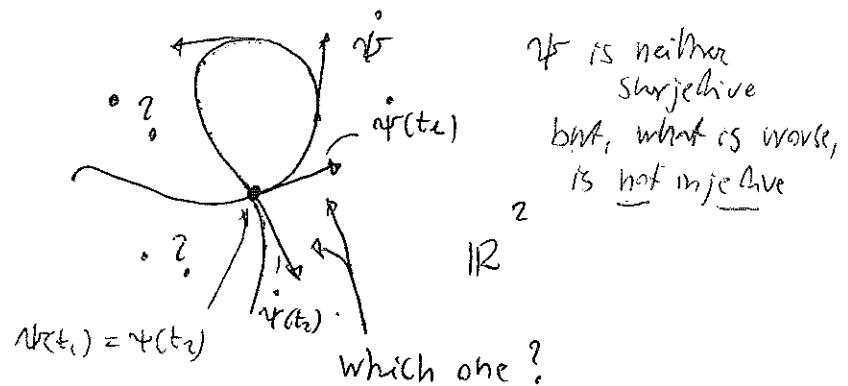
does NOT map vector fields on M to vector fields on N , in general: (although, of course, ψ_* sends tangent vectors to M to tangent vectors to N)



Example

$$\begin{array}{c} \psi \\ \downarrow \\ \text{---} \xrightarrow{\quad t \quad} \text{---} \xrightarrow{\quad t_1 \quad t_2 \quad} \text{---} \\ \text{---} \xrightarrow{\quad t \quad} \text{---} \end{array}$$

$$X = \frac{d}{dt}$$



No problem arises if ψ is a diffeomorphism:

$$(\psi_* X)(f)(y) = X(\psi^* f)(x) = X(\psi^* f)(\psi^{-1}(y))$$

$$\begin{matrix} \wedge & \wedge \\ \mathcal{C}^\infty(N) & \mathcal{C}^\infty(M) \end{matrix}$$

$$x = \psi^{-1}(y)$$

* $\Lambda^k(M)$ | On the other hand, given $\omega \in \Lambda^k(N)$, the pulled-back form $\psi^*\omega \in \Lambda^k(M)$ is always defined (for any ψ smooth). One has:

$$(\psi^*\omega)(x)(x_1 \dots x_k) := \omega(\psi(x))(T_x \psi(x_1) \dots T_x \psi(x_k))$$

(This definition extends the one given in the \mathbb{R}^m -case)