

Lectures on DIFFERENTIAL GEOMETRY AND TOPOLOGY

Manifolds

Lecture XVIII

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We wish to perform differential calculus on $\Delta(M) = \bigoplus_{k=0}^n \Delta^k(M)$ (Grassmann algebra of differential forms on a manifold M); specifically, we want to define operators d , \mathcal{L}_X and \mathcal{I}_X , which will turn exterior differential contraction with $X \in \mathcal{X}(M)$ Lie derivative

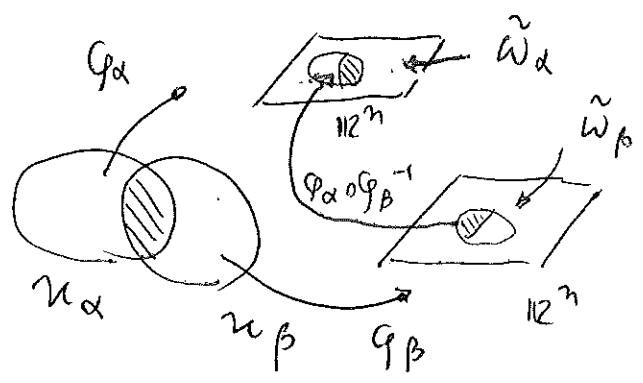
out to be related by Cartan's magic formula

$$\mathcal{L}_X = d \mathcal{I}_X + \mathcal{I}_X d$$

◇ ◇ ◇

Now, $\omega \in \Delta^k(M)$ is given locally by forms $\tilde{\omega}_\alpha$ on \mathbb{R}^n such that

$$\tilde{\omega}_\beta = (\varphi_\alpha \circ \varphi_\beta^{-1})^* \tilde{\omega}_\alpha \quad (\triangle!)$$



Exploiting our knowledge about forms on \mathbb{R}^n , we easily conclude that

We can define d locally, and its definition is well posed:

$$d \tilde{\omega}_\beta = d \{ (\varphi_\alpha \circ \varphi_\beta^{-1})^* \tilde{\omega}_\alpha \} = (\varphi_\alpha \circ \varphi_\beta^{-1})^* d \tilde{\omega}_\alpha$$

(d commutes with pull-back)

and all properties there of persist:

$$\boxed{d^2 = 0} \quad , \quad \boxed{d(\omega \wedge \tau) = d\omega \wedge \tau + (-1)^k \omega \wedge d\tau}$$

$\Delta^k(M) \quad \Delta(M)$

Also observe that, using a partition of unity, a form defined on $U \subset M$ (open) can be extended to a form defined on M .

We wish to give an intrinsic formulation of $d\omega$, $\omega \in \Delta^1(M)$

$$\boxed{d\omega(X, Y) = X\omega(Y) - Y\omega(X) - \omega([X, Y])}$$

Proof. We work locally, so it is enough to take $\omega = u dv$,

$$u, v \in \mathcal{E}^0(M).$$

l.h.s. $d\omega = du \wedge dv$ and

$$\begin{aligned} d\omega(X, Y) &= (du \wedge dv)(X, Y) = (du)(X)(dv)(Y) - (du)(Y)(dv)(X) \\ &= \boxed{X(u)Y(v)} - \boxed{X(v)Y(u)}. \end{aligned}$$

r.h.s. $X\omega(Y) = X[u dv(Y)] = X[u Y(v)]$

$$= \boxed{X(u)Y(v)} + u X(Y(v))$$

$$- Y\omega(X) = -Y[u dv(X)] = -Y[u X(v)]$$

$$= \boxed{-Y(u)X(v)} - u Y(X(v))$$

$$- \omega([X, Y]) = -u dv([X, Y]) = -u [X, Y](v)$$

Thus r.h.s. = ... l.h.s

In general, one shows that, for $\omega \in \Lambda^k(M)$

$$d\omega(x_1, \dots, x_{k+1}) = \sum_{i=1}^{k+1} (-1)^{i+1} x_i \omega(x_1, \dots, \hat{x}_i, \dots, x_{k+1}) \\ + \sum_{i < j} (-1)^{i+j} \omega([x_i, x_j], x_2, \dots, \hat{x}_i, \dots, \hat{x}_j, \dots, x_{k+1})$$

↑
first argument

^: omission

* Interior multiplication (or contraction)

$$i_X : \Lambda^k(M) \rightarrow \Lambda^{k-1}(M)$$

extended to $i : \Lambda \rightarrow \Lambda$

$$\omega \mapsto i_X \omega$$

$X \in \mathfrak{X}(M)$

$$(i_X \omega)(x_1, \dots, x_{k-1})$$

actually, i is a purely algebraic operation.

$$:= \omega(X, x_1, \dots, x_{k-1})$$

↑
first slot

(other notation: $X \lrcorner \omega$)

i_X is linear and, for $X, Y \in \mathfrak{X}(M)$, $\alpha, \beta \in \mathbb{R}$

$$i_{\alpha X + \beta Y} \omega = \alpha i_X \omega + \beta i_Y \omega$$

$$(\diamond) \quad \boxed{i_X^2 = 0}$$

(\diamond\diamond)

and i is an antiderivation

$$\boxed{i_X(\omega \wedge \eta) = i_X \omega \wedge \eta + (-1)^n \omega \wedge i_X \eta}$$

n
 Λ^n

i behaves like d

Let us check that $\tau_X^2 = 0$ $w \in \Delta^{\mathbb{R}}$

$$\begin{aligned} \tau_X (\tau_X w) (x_1, \dots, x_{k-2}) &= \\ &= \tau_X w (x, x_1, \dots, x_{k-2}) = w(x, x, x_1, \dots, x_{k-2}) = 0 \end{aligned}$$

As for (ii), it is enough to check the formula

$$\begin{aligned} \tau_X (w^1 \wedge \dots \wedge w^k) &= \tau_X w^1 \wedge w^2 \wedge \dots \wedge w^k \\ &\quad - \tau_X w^2 \wedge w^1 \wedge \dots \wedge w^k \\ &\quad + \tau_X w^3 \wedge w^1 \wedge \dots \wedge w^k \end{aligned}$$

↑ ↑
1-forms

and this is true by Laplace's formula:

if $x_1 = x$,

$$\begin{aligned} (w^1 \wedge \dots \wedge w^k)(\overset{x}{\underset{x}{\parallel}} x_1, x_2, \dots, x_k) &= \det \left((w^i(x_j)) \right) \\ &= \sum_{i=1}^k (-1)^{i-1} w^i(x_1) \underbrace{(w^1 \wedge \dots \wedge \hat{w}^i \wedge \dots \wedge w^k)(x_2, \dots, x_k)}_{\det \overset{i}{\times} \underset{1}{\hat{1}} \left(\begin{array}{c|c} & \\ \hline & \end{array} \right)} \end{aligned}$$

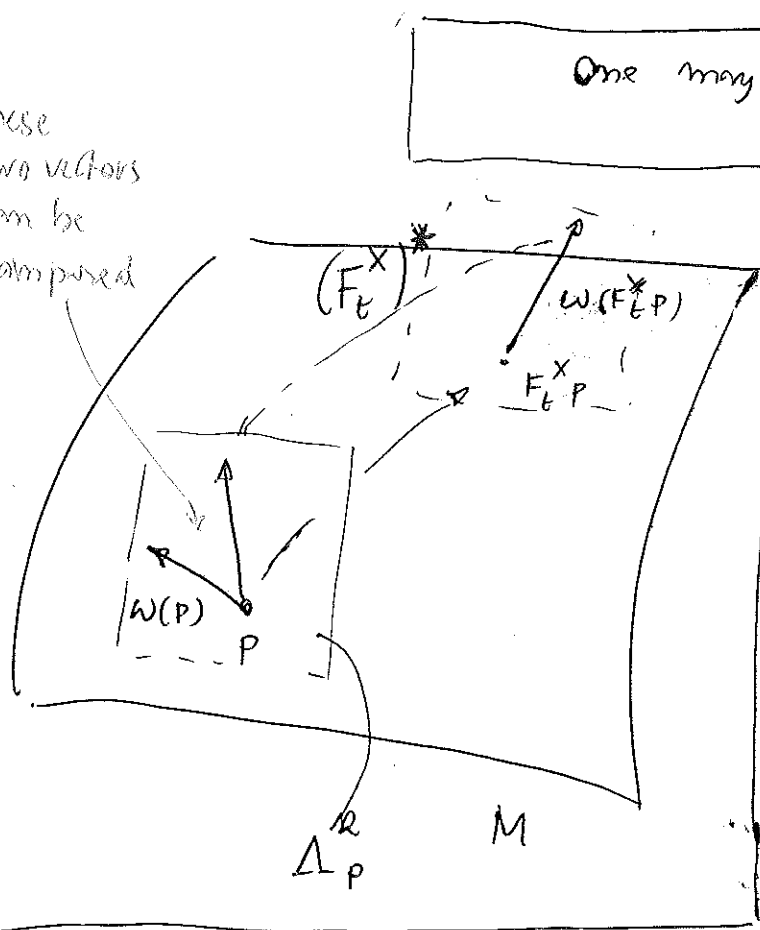
* Lie derivative of a \mathbb{R} -form

Let $X \in \mathfrak{X}(M)$, $\omega \in \Lambda^k(M)$

The Lie derivative of ω along X $L_X \omega \in \Lambda^k(M)$ is defined as:
 F_t^X : flow of X

$$(L_X \omega)(P) = \left. \frac{d}{dt} [(F_t^X)^* \omega] \right|_{t=0} = \lim_{t \rightarrow 0} \frac{(F_t^X)^* \omega(F_t^X \cdot P) - \omega(P)}{t}$$

These two vectors can be compared



One may prove that $L_X(\omega \wedge \tau) =$

$$L_X \omega \wedge \tau + \omega \wedge L_X \tau$$

and, more generally

$$L_X(T \otimes S) = L_X T \otimes S + T \otimes L_X S \quad (*)$$

for any tensor fields

(generalized Leibniz rule)

Also; for a $(0, k)$ -tensor one has:

$$(L_X \sigma)(Y_1 \dots Y_k) = X(\sigma(Y_1 \dots Y_k)) - \sigma([X, Y_1], Y_2 \dots Y_k) - \dots - \sigma(Y_1 \dots Y_{k-1}, [X, Y_k]),$$

This, in turn, coming from

$$X(\sigma(Y_1 \dots Y_k)) = (L_X \sigma)(Y_1 \dots Y_k) + \sigma(L_X Y_1, Y_2 \dots Y_k) + \dots + \sigma(Y_1 \dots L_X Y_k)$$

$L_X(\sigma(Y_1 \dots Y_k))$ Leibniz rule: all arguments are varied one at a time

Let us check (*) in the case of a tensor product of covariant tensors, just to pinpoint the (quite simple) basic idea.

$$\mathcal{L}_X (\sigma \otimes \tau)(P) = \lim_{t \rightarrow 0} \frac{(F_t^X)^* [(\sigma \otimes \tau)(F_t^X(P))] - (\sigma \otimes \tau)(P)}{t}$$

$$= \lim_{t \rightarrow 0} \frac{\overbrace{(F_t^X)^* \sigma(F_t^X(P)) \otimes (F_t^X)^* \tau(F_t^X(P))}^A - \underbrace{\sigma(P) \otimes \tau(P)}_B}{t}$$

$$= \lim_{t \rightarrow 0} \left[\frac{\overbrace{A - \sigma(P) \otimes (F_t^X)^* \tau(F_t^X(P))}^C}{t} + \frac{C - B}{t} \right]$$

[This is the same idea one uses to prove $(fg)' = f'g + fg'$ in calculus]

$$= \lim_{t \rightarrow 0} \frac{\overbrace{(F_t^X)^* \sigma(F_t^X(P)) - \sigma(P)}^{\mathcal{L}_X \sigma}}{t} \otimes \overbrace{(F_t^X)^* \tau(F_t^X(P))}^{\tau(P)} + \sigma(P) \otimes \lim_{t \rightarrow 0} \frac{\overbrace{(F_t^X)^* \tau(F_t^X(P)) - \tau(P)}^{\mathcal{L}_X \tau}}{t}$$

$$= \mathcal{L}_X \sigma \otimes \tau + \sigma \otimes \mathcal{L}_X \tau$$

also recall that in general if $S = \sigma_J^I$, $T = \tau_L^K$

$$S \otimes T = \sigma_J^I \cdot \tau_L^K \quad \leftarrow \text{no summation, just take all products}$$

↑
numerical product

* Theorem Let $\omega \in \Delta(M)$, $X \in \mathcal{X}(M)$.

One has
$$\mathcal{L}_X \omega = d \iota_X \omega + \iota_X d\omega$$

(Cartan's magic formula)

⚠ It holds for forms, not for general tensors (d is not defined...)

Pf. We prove it for $\omega = v dv$. The general case follows by induction.

First of all, notice that

$$(\mathcal{L}_X dv)(Y) = X[\overset{\text{general}}{\text{formula}} dv(Y)] - dv([X, Y])$$

$$= X[Y(v)] - [X, Y](v) = (XY - YX)(v) = Y \underbrace{X(v)}_{\mathcal{L}_X v} = d(\mathcal{L}_X v)(Y)$$

namely

$$\boxed{\mathcal{L}_X dv = d\mathcal{L}_X v}$$

As a corollary, if (x^1, \dots, x^n) are local coordinates and $X = \frac{\partial}{\partial x^1}$,

just to fix ideas, then $\mathcal{L}_X(dx^{i_1} \dots dx^{i_k}) = 0$,

this following from $\mathcal{L}_X dx^j = d\mathcal{L}_X x^j = d\left(\frac{\partial x^j}{\partial x^1}\right)$

and from the general Leibniz rule.

$$\boxed{= d(\delta_{j1}) = 0}$$

Now compute:

$$\begin{aligned}
 \mathcal{L}_X (u dv) (Y) &= (\mathcal{L}_X u \cdot dv + u \mathcal{L}_X dv) (Y) \\
 &= (\mathcal{L}_X u dv + u d \mathcal{L}_X v) (Y) \\
 &= (X(u) dv + u d(X(v))) (Y) \\
 &= X(u) Y(v) + u Y(X(v)) \quad \mathbf{I}
 \end{aligned}$$

Compute II =

$$\begin{aligned}
 &= (i_X d + d i_X) (u dv) (Y) = \\
 &= d (i_X (u dv)) (Y) + i_X d (u dv) (Y) \\
 &= d \left(\underbrace{i_X u}_{\substack{= \\ 0}} dv + u \underbrace{i_X dv}_{X(v)} \right) (Y) + \underbrace{i_X (du \wedge dv)}_{(du \wedge dv)(X, Y)} (Y) \\
 &= d (u X(v)) (Y) + X(u) Y(v) - X(v) Y(u) \\
 &= (du \cdot X(v) + u d(X(v))) (Y) + X(u) Y(v) - X(v) Y(u) \\
 &= Y(u) X(v) + u Y(X(v)) + X(u) Y(v) - X(v) Y(u) \\
 &= X(u) Y(v) + u Y(X(v)) = \mathbf{I} \quad \square
 \end{aligned}$$

Notice that, in general, for forms, one has:

$$\boxed{\mathcal{L}_X d = d \mathcal{L}_X}$$

$$\text{Indeed: } \mathcal{L}_X d = (d i_X + i_X d) d = d i_X d + i_X d^2 = d i_X d$$

$$\text{whereas } d \mathcal{L}_X = d (d i_X + i_X d) = \underbrace{d^2 i_X}_{=0} + d i_X d = d i_X d \quad \square$$