

in \mathbb{R}^3 | Sia

TOPOLOGIA E GEOMETRIA DIFFERENZIALE
Prof. M. Spina a.a. 2009/10

$$\omega =$$

$$dx_1 dy_1 dz$$

forma di volume

Lessione **XXV**

$$x = \alpha \frac{\partial}{\partial x} + \beta \frac{\partial}{\partial y} + \gamma \frac{\partial}{\partial z}$$

$$x_1 - x_2 \quad x_2 - x_3 \quad x_3$$

$$L_X \omega = d i_X \omega + i_X d \omega$$

||
o

$$= d \left[\alpha dy_1 dz - \beta dx_1 dz + \gamma dx_1 dy \right]$$

$$i_{x_1} \omega = \alpha dy_1 dz$$

$$i_{x_2} \omega = -\beta dx_1 dz$$

$$i_{x_3} \omega = \gamma dx_1 dy$$

$$= \frac{\partial \alpha}{\partial x} dx_1 dy_1 dz - \frac{\partial \beta}{\partial y} dy_1 dz dx_1$$



attenzione
non è vero che
in gen..

$$L_{\alpha X} = d L_X$$

$$= \left(\frac{\partial \alpha}{\partial x} + \frac{\partial \beta}{\partial y} + \frac{\partial \gamma}{\partial z} \right) dy_1 dz$$

$$(L_{\alpha X} Y)(t)$$

$$= [i_X Y](t)$$

div X

$$\begin{aligned} &= \alpha X Y(t) - Y(\alpha X(t)) \\ &= \alpha(XY - YX)(t) - Y(\alpha)X(t) \\ &= \alpha [XY](t) - Y(\alpha)X(t) \end{aligned}$$

[A se si moltiplica la
matrice euclidea]

Per una varietà riemanniana

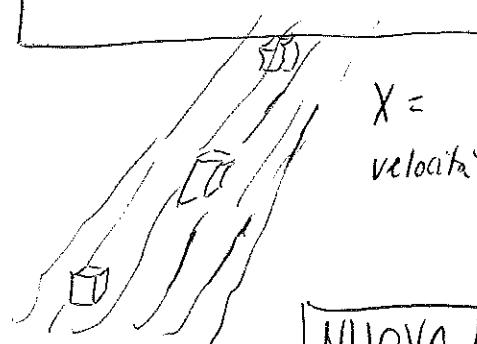
$$L_X \omega_{\text{volg}} = \text{div } X \text{ volg}$$

Infanzia $L_{\alpha X} f = \alpha X(f)$
 $= d L_X f$

X conserva volg $\Leftrightarrow \text{div } X = 0$

Quando in fluido dinamica
 $\text{div} = 0$: incompressibilità del fluido

XXV - 2.



NUOVA