

Lectures on DIFFERENTIAL GEOMETRY AND TOPOLOGY

Manifolds

Lecture III

Tensor product spaces p. 1
(p. 9) tensors p. 4
examples p. 5

* Tensor products

Let V, W (finite dimensional) vector spaces over a field K ($\dim_K V = n, \dim_K W = m$);

their tensor product $V \otimes_K W$ (or $V \otimes W$, if no confusion arises) is defined as follows

$$V \otimes_K W := \left\{ \pi : \begin{array}{c} \downarrow \quad \downarrow \\ V^* \times W^* \end{array} \longrightarrow K / \pi \text{ bilinear} \right\}$$

It is naturally a vector space, generated by π 's of the form

$$v \otimes w \equiv \pi : \begin{array}{ccc} & & \begin{array}{c} V \\ \downarrow \\ \alpha^* \end{array} \\ & & \begin{array}{c} \uparrow \\ V^* \end{array} \\ \begin{array}{c} \dots \\ \uparrow \\ \text{decomposable vectors in } V \otimes W \end{array} & \begin{array}{c} \longrightarrow \\ \pi : \\ \begin{array}{c} \alpha^* \quad \beta^* \\ \uparrow \quad \uparrow \\ V^* \quad W^* \end{array} \end{array} & \begin{array}{c} \longrightarrow \\ \begin{array}{c} \alpha^*(v) \cdot \beta^*(w) \\ \uparrow \quad \uparrow \\ K \quad K \end{array} \\ \text{product in } K \end{array} \end{array}$$

Notice that $d(v \otimes w) = dv \otimes w = v \otimes dw$

$\forall \alpha \in K, v \in V, w \in W$, and

$$(\alpha v_1 + \beta v_2) \otimes w = \alpha (v_1 \otimes w) + \beta (v_2 \otimes w) \text{ etc.}$$

(as maps).

Given, as usual, bases $e = (e_1, \dots, e_n)$, $f = (f_1, \dots, f_m)$ in V and W , resp., it is easily checked that

$e \otimes f \equiv (e_i \otimes f_j)_{\substack{i=1, \dots, n \\ j=1, \dots, m}}$ yields a basis for

$V \otimes W$, i.e., any $\pi \in V \otimes W$ can be written as

$$\pi = \sum_{i,j} c_{ij} e_i \otimes f_j, \text{ for uniquely determined } c_{ij} \in K.$$

Hence $\dim V \otimes W = \dim V \cdot \dim W = n \cdot m$

Notice, in particular, $(e_i \otimes f_j)(e_k^*, f_l^*) = e_k^*(e_i) \cdot f_l^*(f_j) = \delta_{ik} \cdot \delta_{jl}$

and that, if $v = \sum_i \alpha_i e_i$, $w = \sum_j \beta_j f_j$,

then $v \otimes w = \sum_{i,j} \alpha_i \beta_j e_i \otimes f_j$

Important remark

$$\text{Hom}(V, W) \cong W \otimes V^*$$

canonically

This comes from $(W \otimes V^*)(\alpha) = \underbrace{W}_{\downarrow} \otimes \underbrace{V^*}_{\downarrow}(\alpha) = \underbrace{W}_{\downarrow} \otimes \underbrace{V}_{\downarrow}$

leave it as it stands

Concretely, choosing bases

$$w = \begin{bmatrix} \\ \\ \end{bmatrix} \quad m \times 1 \quad v^* = \begin{bmatrix} & & \end{bmatrix} \quad 1 \times n$$

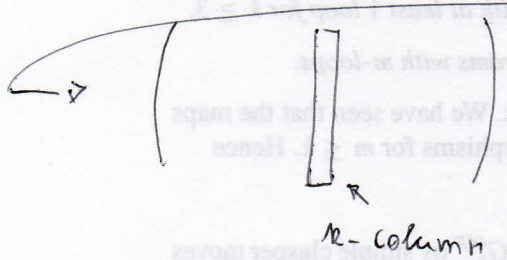
$$w \otimes v^* = \begin{bmatrix} & & \\ & & \\ & & \end{bmatrix} \quad m \times n \text{ matrix}$$

matrix product

$$w \otimes v^* = \left\{ \sum_{i,j} a_{ij} (f_i \otimes e_j^*) \right\}$$

$$\sum_{i,j} a_{ij} (f_i \otimes e_j^*) (\cdot, e_k) = \sum_{i,j} a_{ij} \underbrace{e_j^*(e_k)}_{\delta_{jk}} f_i$$

$$= \sum_i a_{ik} f_i, \text{ i.e. } e_k \mapsto \sum_i a_{ik} f_i$$



of the matrix representation
of a homomorphism T

One can naturally define $V_1 \otimes V_2 \otimes V_3$ etc.

either directly or via $(V_1 \otimes V_2) \otimes V_3$

(canonically isomorphic to $V_1 \otimes (V_2 \otimes V_3)$) and concluding by induction.

We shall stick to the case in which $V_i = V$ or V^*

Define the space of (p, q) -tensors, $\mathcal{T}_{p,q} = \underbrace{V^* \otimes \dots \otimes V^*}_q \otimes \underbrace{V \otimes \dots \otimes V}_p$

contravariance index covariance index

notice

$$\mathcal{T}_{p,q} = \left\{ \pi: \underbrace{V \times V \times \dots \times V}_q \times \underbrace{V^* \times \dots \times V^*}_p \rightarrow K \mid \pi \text{ multilinear, i.e. linear in each argument} \right\}$$

$V \otimes V^* \cong V^* \otimes V$
canonically

$V \otimes V \otimes V^* \cong_{\text{can}} V \otimes V^* \otimes V$

$V^* \otimes V \otimes V \cong_{\text{can}} V^* \otimes V \otimes V$

$V \otimes V^* \otimes V$
etc.

$T \in \mathcal{T}_{p,q}$ is p -times contravariant
 q -times covariant

Fixing a basis $e = (e_1, \dots, e_n)$ in V ,
together with the dual basis
 $e^* = (e_1^*, \dots, e_n^*)$, we have


$$T = \sum_{I, J} T_{J, I}^{i_1 \dots i_p} e_{j_1}^* \otimes \dots \otimes e_{j_q}^* \otimes e_{i_1} \otimes \dots \otimes e_{i_p}$$

$I = (i_1, \dots, i_p)$
 p -multiindex..

$J = (j_1, \dots, j_q)$
 q -multiindex

Components of T with respect to
the basis $(e^{j_1} \otimes \dots \otimes e^{j_q} \otimes e_{i_1} \otimes \dots \otimes e_{i_p})$

Schematically: $T = T_J^I e^J \otimes e_I$

notice that $e_j^* \mapsto e^j$ 

Einstein's convention

this notation would be more appropriate

III-4

★ Examples $V, V^*, \text{End}(V) \cong V \otimes V^* \cong V^* \otimes V$
 endomorphisms

are easily recovered.

$$\boxed{V = \mathcal{L}_{1,0}} \quad , \quad \boxed{V^* = \mathcal{L}_{0,1}}$$

$$\boxed{\text{End}(V) \cong \mathcal{L}_{1,1}}$$

notice $m_{1,1}$ i : row index

$$T = \begin{pmatrix} a_j^i \end{pmatrix} \quad V = \alpha^i e_i \quad a_j^i \begin{matrix} \leftarrow \text{row index} \\ \leftarrow \text{column index} \end{matrix}$$

↑ notice $m_{1,1}$ ↑ Einstein's conv.

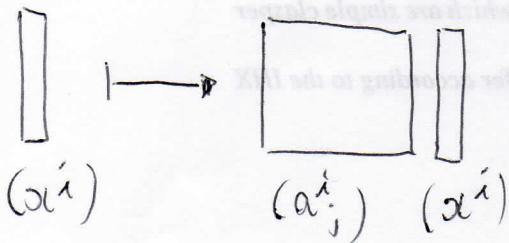
$$T = a_j^i e^j \otimes e_i$$

★ Compute TV , using tensor notation (Einstein's convention being employed throughout)

$$\begin{pmatrix} a_j^i e^j \otimes e_i \end{pmatrix} (\alpha^k e_k) \stackrel{\text{Einstein}}{=} a_j^i \alpha^k e^j (e_k) e_i = a_j^i \alpha^k \delta_{jk} e_i$$

$e_j^*(e_k)$
||
 δ_{jk}

$$= a_j^i \alpha^j e_i \Rightarrow (\alpha^i) \mapsto (a_j^i \alpha^j)$$



* Another example (crucial in Riemannian geometry)

$\langle \cdot, \cdot \rangle$ inner product on a Euclidean vector space V

$\langle \cdot, \cdot \rangle$ is a $(0,2)$ -tensor $\langle \cdot, \cdot \rangle: V \times V \rightarrow \mathbb{R}$
bilinear

upon choosing a basis $e = (e_1, \dots, e_n)$ (+ symmetric
+ positive definite)

$$v = x^i e_i$$

$$w = y^j e_j$$

$$\langle e_i, e_j \rangle = g_{ij}$$

$$\langle v, w \rangle = g_{ij} x^i y^j$$