MAPPATURA CERSI-CEIS

COMPUTER ENGINEERING FOR ROBOTICS AND SMART INDUSTRY	COMPUTER ENGINEERING FOR INTELLIGENT SYSTEMS	
Insegnamento a libretto	Insegnamento	Docente
Dynamic systems	Dynamic systems	Riccardo Muradore
Machine learning & Artificial intelligence	NO (contattare docente per vecchio esame)	Francesco Setti
Discrete Event and Hybrid Systems	NO (contattare docente per vecchio esame)	Franco Fummi
Industrial plants & Production management	Industrial plants & Production management	lacopo Tamellin
Embedded & IoT Systems Design	Embedded & IoT Systems Design	Franco Fummi
Embedded Operating Systems	Embedded Operating Systems	Graziano Pravadelli
Networked Embedded & IoT Systems	Networked embedded & IoT systems	Davide Quaglia
Advanced Computer Architectures	Computer architectures and programming for intelligent systems	Nicola Bombieri
Robotics	Robotics	Andrea Calanca
Computer vision	Computer Vision	Francesco Setti
Physical Human-Robot Interaction	Physical Human-Robot Interaction	Andrea Calanca
Advanced Control Systems	Advanced Control Systems	Riccardo Muradore
Process Monitoring	NO (contattare docente per vecchio esame)	Francesco Setti
Human computer interaction	Extended Reality and Advanced Interaction	Andrea Giachetti
Advanced Database & Information Systems	Data management and machine intelligence – MODULO Data Management Systems	Carlo Combi
Digital design	Advanced visual computing and 3d modeling	Andrea Giachetti
Data Warehouse and Integration	NO (contattare docente per vecchio esame)	Carlo Combi
Cyber-security for IoT	Cyber-security for IoT	Michele Pasqua
Data Visualization	NO (contattare docente per vecchio esame)	Andrea Giachetti
Deep Learning	Data management and machine intelligence – MODULO Deep Learning	Francesco Setti
Electronic devices and Sensors	Electronic devices and Sensors	Francesco Enrichi
Mobile Robotics	Mobile Robotics	Alessandro Farinelli
Organization Studies	NO (contattare docente per vecchio esame)	Serena Cubico
Robotics, Vision and Control	Robotics, Vision and AI	Francesco Setti
Robot programming and control	NO (contattare docente per vecchio esame)	Andrea Calanca
Systems design laboratory	NO (contattare docente per vecchio esame)	Graziano Pravadelli
Systems Verification & Testing	Systems Verification & Testing	Franco Fummi
Material Science	Materials Science	Stefano Gialanella

MAPPING CERSI-CEIS

COMPUTER ENGINEERING FOR ROBOTICS AND SMART INDUSTRY	COMPUTER ENGINEERING FOR INTELLIGENT SYSTEMS	
Booklet teaching	Teaching	Lecturer
Dynamic systems	Dynamic systems	Riccardo Muradore
Machine learning & Artificial intelligence	NO (contact lecturer for old exam)	Francesco Setti
Discrete Event and Hybrid Systems	NO (contact lecturer for old exam)	Franco Fummi
Industrial plants & Production management	Industrial plants & Production management	lacopo Tamellin
Embedded & IoT Systems Design	Embedded & IoT Systems Design	Franco Fummi
Embedded Operating Systems	Embedded Operating Systems	Graziano Pravadelli
Networked Embedded & IoT Systems	Networked embedded & IoT systems	Davide Quaglia
Advanced Computer Architectures	Computer architectures and programming for intelligent systems	Nicola Bombieri
Robotics	Robotics	Andrea Calanca
Computer vision	Computer Vision	Francesco Setti
Physical Human-Robot Interaction	Physical Human-Robot Interaction	Andrea Calanca
Advanced Control Systems	Advanced Control Systems	Riccardo Muradore
Process Monitoring	NO (contact lecturer for old exam)	Francesco Setti
Human computer interaction	Extended Reality and Advanced Interaction	Andrea Giachetti
Advanced Database & Information Systems	Data management and machine intelligence – MODULE Data Management Systems	Carlo Combi
Digital design	Advanced visual computing and 3d modeling	Andrea Giachetti
Data Warehouse and Integration	NO (contact lecturer for old exam)	Carlo Combi
Cyber-security for IoT	Cyber-security for IoT	Michele Pasqua
Data Visualization	NO (contact lecturer for old exam)	Andrea Giachetti
Deep Learning	Data management and machine intelligence – MODULE Deep Learning	Francesco Setti
Electronic devices and Sensors	Electronic devices and Sensors	Francesco Enrichi
Mobile Robotics	Mobile Robotics	Alessandro Farinelli
Organization Studies	NO (contact lecturer for old exam)	Serena Cubico
Robotics, Vision and Control	Robotics, Vision and Al	Francesco Setti
Robot programming and control	NO (contact lecturer for old exam)	Andrea Calanca
Systems design laboratory	NO (contact lecturer for old exam)	Graziano Pravadelli
Systems Verification & Testing	Systems Verification & Testing	Franco Fummi
Material Science	Materials Science	Stefano Gialanella